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FINITE ELEMENT ANALYSIS OF F-16 BALLISTIC TESTS

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FOREWORD

This technical report was prepared by Mr. Gordon R. Negaard for Anamet Laboratories, Inc. under Purchase Order No 5963. the technical effort reported herein was performed as a part of Problem No. 4.2-26 of Air Force Contract No. F33615-84-C-3216 under which Anamet Laboratories, Inc. operates the Aerospace Structures Information and Analysis Center (ASIAC), for the Flight Dynamics Laboratory at Wright-Patterson Air Force Base in Ohio.

The objective of this investigation was a finite element analysis of F-16 ballistic tests. The investigation involved modeling of damage cases based on test results, modeling of patches to repair the damage, and a NASTRAN static and dynamic analysis. Stresses and displacements were obtained from a static analysis, and the natural frequencies of the models were obtained from a dynamic analysis.



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1.0 INTRODUCTION

Analytical vulnerability techniques are intended to postulate and study damage to aircraft structures and attempt to predict the operational effects of such damage. For this study, a finite element analysis was used to quantify and evaluate the effects of real damage observed from live firings on an F-16 wing. The results are published in this report for comparison with test data from the live firings.

Each damage case was modeled by modifying the model by removing finite elements corresponding to the hole and by weakening damaged elements to approximate the damage from test data. A static analysis was then performed to calculate the residual strength degradation caused by the observed damage. A dynamic analysis was then used to calculate the changes in fundamental frequencies of the model. Combining these two effects, one can predict a reduction in the safe maneuver envelope in terms of maneuver load factor and airspeed. This technique can also be used to assess damage from various weapons in order to extend the study of experimental damage to simulation studies.

It must be cautioned that considerable experience and engineering judgment are required to model the damage and evaluate the effects. Benchmark studies are useful in order to establish confidence in the ability to predict damage effects using analytical techniques, and in providing procedures and guidelines in the use of such techniques. A large amount of detail has been included in this report in the hope that it will serve as such a benchmark.

2.0 DISCUSSION OF THE FINITE ELEMENT MODEL

It should be remembered that a finite element model is merely a mathematical model of a structure. It is an approach which allows one to solve complex problems, beyond the reach of classical analysis. The model is only an approximation of the actual structure, created by breaking the structure down into

smaller pieces such as plates, shells, rods, and bars, each of which can be analyzed by classical means. It is generally accepted that finite element results should be accurate within five per cent for static analysis for a complex structure.

Finite element models should really be divided into two groups, internal loads models and dynamic models. An internal loads model looks much like the actual structure and is usually the type model meant when referring to a "finite element model." Displacements and forces are obtained at nodal or grid points. Stresses within the idealized structures representing wing skin, spar caps, and spar webs are also obtained. To get results around cutouts, cracks in bolts or fittings, etc., an analyst usually takes the internal forces that have been obtained for the total structure and uses traditional hand analysis to obtain stresses. In the case of complicated parts, one may go to a much more detailed model. As an example, one may use solid elements to subdivide the structure into much smaller pieces to obtain stresses in areas of stress concentration. A dynamic model, on the other hand, may not look much like the actual structure. wing, for example, may be modeled as a single beam, with bending and torsional stiffnesses of the finite elements representing those of the cross-section of the wing. Such a model obtains quite accurate frequencies and mode shapes for dynamic analysis. It can also be used to obtain wing root bending moments and shears, for example, but it is not useful for internal stresses. A dynamic model has the advantage that a small dynamic model gives quite accurate results for its purposes in comparison to the size of the model needed to obtain internal loads and stresses.

2.1 The F-16 Wing Model

A finite element model of the F-16 wing obtained from General Dynamics was used for this study. The model represents a fully configured wing which includes the wingtip missile launcher, pylons, and some nonstructural weight. The internal primary structure of the wing is shown in Figure 1. As this drawing illustrates, the F-16 wing is of multispar construction with very little in the way of ribs except where hard points are necessary for attachment points. The wing skin thickness varies from 0.5 inches inboard to 0.2 inches outboard. This thickness allows the wing to carry a major portion of the the wing bending moment and torsion. In addition, the wing skin and multiple spar construction provide multiple load paths, allowing considerable load redistribution in the event of damage to the skin and one or more spars. For the tests, the wing was supported in a cantilever fashion at Butt Line (BL) 41.5. Test loads were applied along BL 120.0 where a series of hard points for a pylon are located.

The NASTRAN finite element model used is a conventional membrane, shear panel, and rod representation with a few bar elements added where necessary. The complete model has a total of 1043 elements and 384 grid points. The model is rigidly constrained at BL 41.5 to simulate the cantilever condition. These constraints are located at Fuselage Stations (FS) 308.5, 324.5, 340.5, and 356.5 and represent bolt attach points. These locations vary slightly from that shown in the test plan (Ref. 1) where these points are listed as FS 309.8, 325.8, 341.8, and 357.8. This difference is probably due to the construction of the finite element model. The modelers placed the constraints at the end of the ribs rather than adding extra grid points and elements to locate the constraints more precisely. The effect should be unimportant, especially at any distance from the constraints. Even at the area of the constraints, a detailed stress analysis would probably find little error.

2.2 Validation of the Model

In order to use a finite element model with confidence, it is necessary to be able to compare it against some known data. In this case, although the finite element model appeared to be a

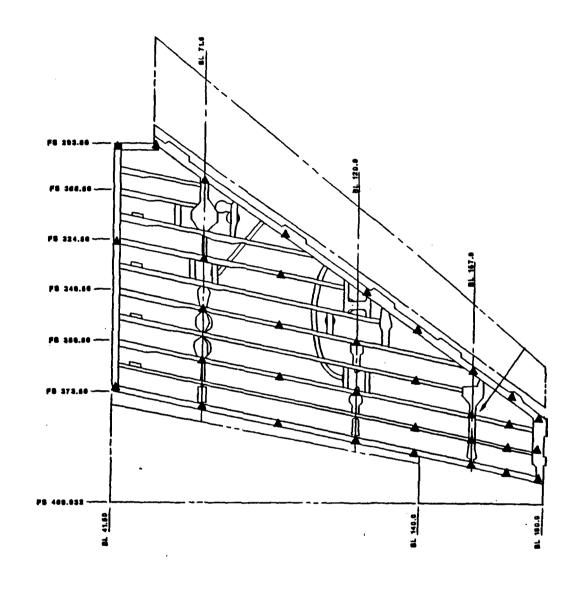


Figure 1. Structural Layout of the F-16 Wing

good representation of an F-16 wing, it was first necessary to convert it from MSC/NASTRAN into a COSMIC/NASTRAN version in order to run it on the WPAFB version of NASTRAN. These changes, although minor, needed to be checked out. It was also necessary to make further modifications to this model so that it would represent the actual structures under test. The three test articles, referred to as Wing #1, Wing #2, and Wing #3, had been stripped of all external structure including the leading and trailing edge flaps. These wings were considerably lighter than the fully configured wing. It was necessary to create four versions of the F-16 wing finite element model. The first two models were used to validate the finite element analysis and insure that the finite element model adequately represented the real structure under test. The other two models were used to represent the test articles. These finite element models are referred to as Models D-1, D-2, D-3, and D-4. The D designation is used to indicate that they were used primarily for dynamic analysis.

A model would normally be validated using a known set of loads and measuring experimental deflections against those calculated by the model. This was attempted first using a 30,000 pound or 6g load. The NASTRAN analysis indicated a displacement of about 2.7 inches at BL 120.0 while experimental data showed about 5.0 inches. This is at least partly because, while a mathematic model can be rigidly constrained, the real structure has small but finite rotations and displacements at the cantilevered support. An attempt was made to measure these displacements, but an analysis shows that the measured rotations of 0.15 degrees should cause only about 0.15 inches in vertical displacement at BL 120.0 (See Figure 2). Measurement of small rotations of this magnitude is a very difficult task, even under laboratory conditions. It was decided that a comparison of dynamic effects would be easier to make.

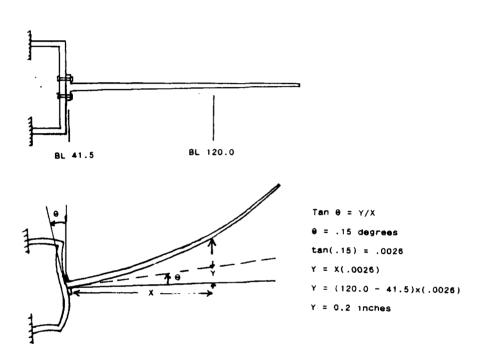


Figure 2. Rotation of Test Fixture Under Load

2.3 Dynamic Analysis of the Model

After being converted from MSC NASTRAN, the original model, referred to as Model D-1, was checked out and compared to a ground vibration test documented in AFWAL FIBG-TM-83-187 (Ref. 2) where the wing was of a similar configuration. The missile launcher and pylons were then removed to make a further comparison with a clean F-16 wing documented in a General Dynamics memorandum (Ref. 3). This model is referred to as Model D-2. Two additional models were then made to simulate the test wings. In addition to removing attached structures such as flaps and ailerons, some nonstructural weight was also removed in order to match the weights of the actual test articles for the F-16 wing ballistic test. These two models are referred to as Models D-3 and D-4 and refer to Wing #1 and Wing #2, respectively, in the test plan.

The following summary of these models may help clarify their characteristics and their use:

- Model D-1: This is a complete model of an F-16 wing including the Wingtip Missile Launcher. The model weight is 1753 pounds.
- Model D-2: The structure is the same as Model D-1 except that the missile launcher and pylon are removed. This model is approximately the same as the one described in Reference 3. Some nonstructural weight had to removed to get the model down to the stripped wing weight which was determined to be approximately 1038 pounds.
- Model D-3: This is Model D-2 except that both front and rear flaps are removed. This model is essentially a stripped torque box and weighs 840 pounds. This model represents the wing used for tests 1 through 7 and referred to in the test plan as Wing #1.

Model D-4: Model D-3 except that the remaining outboard section of the rear flap was removed and weighs 830 pounds. This model represents the wing used in tests 8 through 17 and referred to in the test plan as Wing #2.

Plots of the finite element models of these four wing models are shown in Figures A-1 through A-4. Dynamic runs were made to determine the lowest four natural frequencies of each model. Table 1 contains a list of the lowest four calculated modes for the dynamic runs of the finite element models D-1 and D-2 with a comparison with the results given in References 2 and 3. The first four modes for models D-3 and D-4 are also included in this table.

Plots of the mode shapes for all four models are included as Figures A-5 through A-20 in Appendix A. It can be noticed that first and second wing bending are the two lowest modes, with the first torsional mode only slightly higher than the second bending mode. It would be possible for these two modes to cross and even interact if the torsional stiffness was degraded significantly. This could strongly affect flutter speed. The agreement between model D-1 and the FIBG analysis can be seen to be fairly close. So is the agreement between model D-2 and the General Dynamics analysis of the stripped wing. Based on these results, Models D-3 and D-4 should simulate the behavior of the two test wings fairly accurately.

2.4 Static Analysis of the Model

For the static analysis, a 30,000 pound load was applied to the finite element model at BL 120.0. This load was matched to the test load as closely as possible in magnitude and location. The values of the applied load for the model were arrived at by averaging the measured values at the three load cells over several experimental tests. These loads are compared as follows:

TABLE 1

COMPARISON OF FIRST FOUR SYMMETRIC MODES (HERTZ)

FOR MODELS D-1 THROUGH D-4

Case	WT(1bs)	First	Second	Third	Fourth
Model D-1 Ref. 2	1753	4.66 5.08	7.80 7.57	15.66	21.16
Model D-2 Ref. 3	1038	10.03	26.97 34.76	32.99 36.51	41.44 56.16
Model D-3 Model D-4	840 830	10.52 10.94	35.29 37.28	45.59 48.15	70.47 77.16

	Load Cell No.			
	1	2	3	
Load Cell Location (FS)	340.0	361.0	380.0	
Model Load Location (FS)	341.9	362.6	378.6	
Load (pounds)	17000	10000	3000	

This table shows that the location of the model loads duplicated the test loads within an inch or two. The bending moment, torsion, and shear for the NASTRAN analysis should therefore match the test conditions very closely. For each model, the bending moment, torsion, and shear at the wing root were calculated by summing the constraint forces from NASTRAN. These constraint forces varied slightly depending on the load paths in each damage case; however the total bending moment, torsion, and shear stayed almost constant, as would be expected. The summation of the forces for the undamaged wing D-3 is compared with the test plan as follows:

	NASTRAN	<u>Test Plan</u>
Bending Moment	2,398,642 in.1bs	1,500,000 in.lbs
Torsion	9,564,664 in.lbs	700,000 in.lbs
Shear	30,000 lbs	30,000 lbs

Comparing these data, it would appear that the bending moment for the model loads is somewhat too high, but the torsion is an order of magnitude too high. In order to reduce the torsion, the applied load at BL 120.0 would have to be moved considerably forward, bringing it off of the actual wing. This is the result of trying to replace a distributed load with a few concentrated loads. A compromise usually has to be made in a case like this.

Plots of the displacements at BL 120.0 are included in all the damage cases for comparison with measured displacements. The calculated displacements of undamaged Wing #1 (Model D-3) can be seen in Appendix C, while the displacements for undamaged Wing #2 (Model D-4) can be seen in Appendix H. They are almost identical and range from about 2.40 inches at the leading edge to 2.74 inches at the trailing edge, a total of about one-third of an inch. Two interesting observations can be made from the plots in Appendices C and H. First, the wing warps under the applied load, creating a "washout condition." Second, the leading edge of the model deflects more than expected. This may be because the leading edge of the model is modeled too soft, but more likely, it is because the major load (17,000 pounds) is applied here. This amount of wing warping is probably due only to the test loads and would not occur under distributed air loads.

Contour plots of the stresses in the upper and lower skin surfaces were created to help illustrate the change in load path and stress pattern for each damage case and for comparison with strain data on the tests. The NASTRAN results matched this strain data quite well. Plots of the upper and lower wing surfaces and contour plots of the stresses on both surfaces are contained in Appendix B for both Models D-3 and D-4, although the differences between them are very small.

3.0 ANALYSIS OF THE DAMAGE

The damage cases are referred to as DC-1, etc., where the numbers correspond to the number of each test shot. DC-1R refers to the damage case model after modeling the repair to the wing. DC-1R therefore becomes the baseline or "before damage" case for DC-2 just as Model D-1 was the "before damage" case for DC-1. Some of the planned test shots were eliminated or consolidated, and some were not modeled, so although the damage cases run from DC-1 to DC-17, there are some gaps in the numbering of the cases.

DC-1, DC-2, DC-3, DC-4, and DC-7 represent the test shots on Wing #1. DC-9 and DC-12 represent the test shots on Wing #2, while DC-15, DC-16, and DC-17 are the test shots on Wing #3. The wings were not repaired after shots #7 and #17 so there are no repaired cases for those two shots. A separate appendix was prepared for each damage case (Appendices C through L) because of the large amount of material included. A short summary of the results of each case will be given here but the reader is referred to the appendices for plots, tables and details. For an in-depth understanding of each case, one needs to look at the locations, size, and pattern of the damaged areas, study the contour plots for the load paths and stress patterns, and compare the displacement plots and first torsional modes of the damage case to the before and after rases.

3.1 Analysis Procedure

The damage cases were modeled by removing upper and lower skin surface to represent the missing or cracked areas of the skin. The spars and ribs were either weakened or removed to represent internal damage. Both static and dynamic runs were made of each damage case to obtain stresses, displacements, and natural frequencies. The damaged model was then repaired to match the actual patch applied to the test article. Subsequently, static and dynamic analyses were performed on the repaired structure. The next damage case was then modeled using the previously repaired wing model to simulate the actual test item.

Plots illustrating the modeling of the damage to the upper and lower wing surfaces are included in each appendix. Contour plots of the stresses on both surfaces and plots of the first four mode shapes are also included. A summary of the results for each damage case compares the displacements under the applied load before test, after test, and after repair. A comparison is then made of the change in residual strength and the change in torsional frequency. For elastic analysis, wing strength can be

calculated as being inversely proportional to its deflection under load. Residual strength degradation can be calculated as a percentage of the original strength by dividing the change in displacement by the original displacement. Calculation of flutter effects is much more difficult since flutter is a very complex topic. One generalization that can be made is that flutter is generally directly proportional to the first torsional frequency. One can therefore make the assumption that a reduction in flutter speed will be directly proportional to the change in first torsional frequency divided by the original frequency. This summary is also included in each damage case.

3.2 Results of Damage Case 1

This shot was near the rear spar. Damage effects were minor. Very little wing skin was removed from the top or bottom surface. There was also very little spar damage. The change in residual strength and torsional strength was less than one per cent.

3.3 Results of Damage Case 2

This shot was slightly forward and a little inboard of damage case 1. There was slightly more surface removed and a little more spar damage but the damage effects were still minor. The change in both residual strength and torsion was approximately two per cent.

3.4 Results of Damage Case 3

This shot damaged a large amount of skin on the top surface as well some spars. Its location near the front spar apparently wiped out other load paths and caused the front spars to carry additional load as evidenced by the spike in the deflection pattern. Even after modeling the repair, this was still evident.

The change in residual strength was about 23 per cent while the change in torsional strength was about 35 per cent. This change in torsional strength can be seen in the plot of deflections in Figure E-1 where the amount of "washout" has decreased. The damage was obviously in front of the torsional axis of the wing to produce this effect. The effect of the change in stress contour pattern is also obvious in Figure E-4.

3.5 Results of Damage Case 4

This shot appeared to do considerable damage to the inboard section of the front spar; however the analysis did not indicate the damage to be very severe. The damage is apparently not in a heavy load-carrying area, which is confirmed by the stress contours. The residual strength change was about six per cent while the torsional effect was less than two per cent.

3.6 Results of Damage Case 7

There was considerable skin damage here, particularly on the upper surface; however the damage runs parallel to the spars so the effect on load-carrying capability was less than first suspected. The residual strength change was about five per cent while the torsional effect was only about two per cent.

3.7 Results of Damage Case 9

This damage was in the inboard area near the rear edge. This is in area of high stress concentration and also quite far behind the torsional axis. Thus the damage, although not very severe, had a pronounced effect, especially on torsion. The residual strength change was only six per cent, but the torsional change was about 27 per cent.

3.8 Results of Damage Case 12

This shot appears to be near the torsional axis. The damage was quite severe, causing about a 20 per cent reduction in residual strength. The torsional change was less than four percent, however. Considerable skin was damaged on both top and bottom surfaces, but the damage to the bottom surface ran parallel to the spars, so the effect was minimized.

3.9 Results of Damage Case 15

The effects of this shot could be rated as minor to moderate. The residual strength change was about three per cent while the torsional change was about four per cent. The displacement plot in Figure J-1 shows the torsional effect very clearly even if it is small.

3.10 Results of Damage Case 16

The major damage was to the lower surface. The damage was not too severe and was also near the torsional axis. The residual strength reduction was about eight per cent while the torsional reduction was only about four per cent.

3.11 Results of Damage Case 17

This case was the most severe of those evaluated. It had the largest amount of damage to both wing surfaces. Two spars were completely severed and two more badly damaged. The loss in residual strength was almost 45 per cent, yet the torsional loss was only four per cent.

4.0 SUMMARY

A finite element analysis was conducted on ten damage cases modeled on test results from live firings on an F-16 wing. Stress and displacement results were obtained from static analysis and the natural frequencies of the models were obtained from a dynamic analysis. A comparison was made of residual strength degradation and changes in the natural modes of the damaged and undamaged models. Detailed results are contained in the appendices of this report. For convenience, a summary of the displacements for all the damage cases is contained in Table 2 and a summary of the first four symmetric modes of all the models is contained in Table 3.

TABLE 2
VERTICAL DISPLACEMENTS AT BL 120
FOR THE DAMAGE CASES

FS	387.9	378.6	370.6	362.6	354.6	349.7	346.6	341.9
D-3	2.74	2.71	2.63	2.66	2.49	2.43	2.40	2.55
DC-1	2.76	2.72	2.65	2.67	2.49	2.44	2.40	2.56
DC-1R	2.74	2.71	2.63	2.66	2.48	2.43	2.39	2.55
DC-2	2.82	2.79	2.71	2.74	2.55	2.49	2.45	2.60
DC-2R	2.76	2.73	2.65	2.68	2.50	2.44	2.41	2.56
DC-3	3.24	3.18	3.16	3.16	3.12	3.10	3.37	3.11
DC-3R	2.66	2.59	2.56	2.56	2.50	2.48	2.74	2.48
DC-4	2.79	2.74	2.71	2.71	2.67	2.65	2.91	2.68
DC-4R	2.70	2.64	2.61	2.61	2.56	2.54	2.80	2.54
DC-7	2.83	2.78	2.75	2.75	2.70	2.68	2.95	2.71
D-4	2.74	2.71	2.63	2.66	2.55	2.40	2.43	2.49
DC-9	3.02	2.95	2.83	2.83	2.67	2.52	2.56	2.63
DC-9R	2.77	2.73	2.65	2.67	2.55	2.40	2.43	2.49
DC-12	3.30	3.25	3.16	3.17	2.99	2.92	2.88	3.04
DC-12R	2.66	2.63	2.55	2.57	2.40	2.34	2.31	2.46
DC-15	2.87	2.83	2.74	2.75	2.55	2.49	2.45	2.60
DC-15R	2.75	2.71	2.64	2.66	2.49	2.43	2.40	2.55
DC-16	2.92	2.90	2.83	2.87	2.70	2.65	2.62	2.79
DC-16R	2.78	2.74	2.67	2.70	2.53	2.47	2.44	2.59
DC-17	3.97	3.88	3.76	3.73	3.49	3.39	3.32	3.51

TABLE 3

COMPARISON OF FIRST FOUR SYMMETRIC MODES (HERTZ)

FOR THE DAMAGE CASES

Case		WT(1bs)	First	Second	Third	Fourth
Model	D-3	840	10.52	35.29	45.59	70.47
Model	DC-1	832	10.49	35.26	45.15	70.21
Model	DC-1R	835	10.54	35.28	45.62	70.48
Model	DC-2	834	10.45	34.94	44.75	66.75
Model	DC-2R	837	10.55	35.05	45.56	70.38
Mode1	DC-3	830	9.54	29.64	38.11	47.23
Mode1	DC-3R	838	10.54	35.23	47.02	70.67
Mode1	DC-4	835	10.33	34.64	46.22	68.04
Mode1	DC-4R	838	10.47	35.06	46.93	70.42
Mode1	DC-7	831	10.24	34.61	46.04	67.33
Model	DC-9	827	10.42	31.60	35.02	48.06
Model	DC-9R	831	10.76	35.06	45.67	65.79
Mode1	DC-12	827	9.88	34.14	43.87	66.29
Mode1	DC-12R	832	10.86	34.87	45.54	65.37
Model	DC-15	829	10.82	36.69	46.10	73.39
Model	DC-15R	832	10.93	37.28	48.12	77.50
Model	DC-16	828	10.89	36.10	46.13	76.37
Model	DC-16R	831		37.50	48.13	78.37
Model	DC-17	822	8.96	36.21	46.64	75.70

REFERENCES

- 1. Ritter, S. B., "Detailed Test Plan for Aircraft Joint Live Fire (JLF) Test," JLF-TP-16-S-1, September 1986.
- 2. Wright, R. L., "Ground Vibration Test of the AFWAL GF-16," AFWAL-TM-83-187-FIBE, April 1985.
- 3. LeBlanc, D. J., "F-16 Wing Frequency Data for Joint Live Fire Program," General Dynamics Memorandum, 28 May 1987.

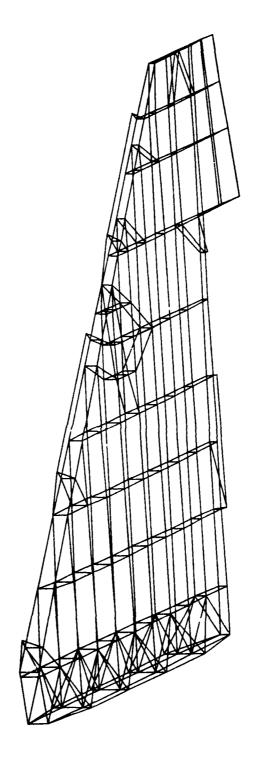
APPENDIX A

DYNAMIC ANALYSIS OF F-16 WING MODELS

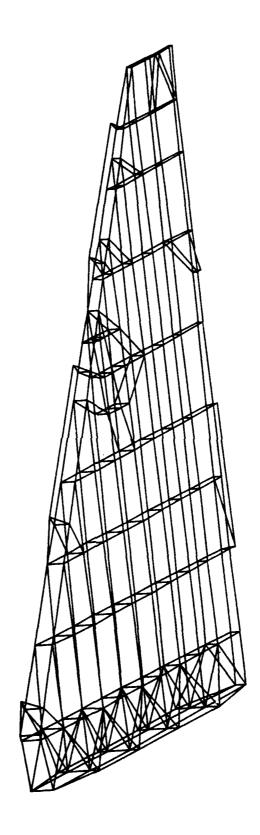
Figure A-1. Finite Element Model D-1

A-2

Figure A-2. Finite Element Model D-2



A-4



4.66 Hertz Symmetric Normal Modes for F-16 Wing Model D-1 Frequency = Givens Method Mode 1

Figure A-5. 1st Wing Bending Mode (Model D-1)

Symmetric Normal Modes for F-16 Wing Model D-1 Givens Method Mode 2 Frequency = 7.80 Hertz

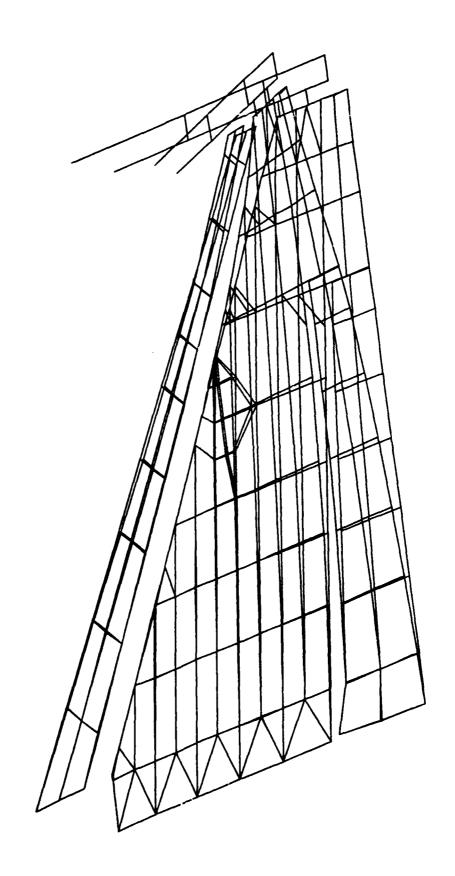


Figure A-6. Missile Pitch Mode (Model D-1)

Symmetric Normal Modes for F-16 Wing Model D-1 Givens Method Mode 3 Frequency = 15.66 Hertz

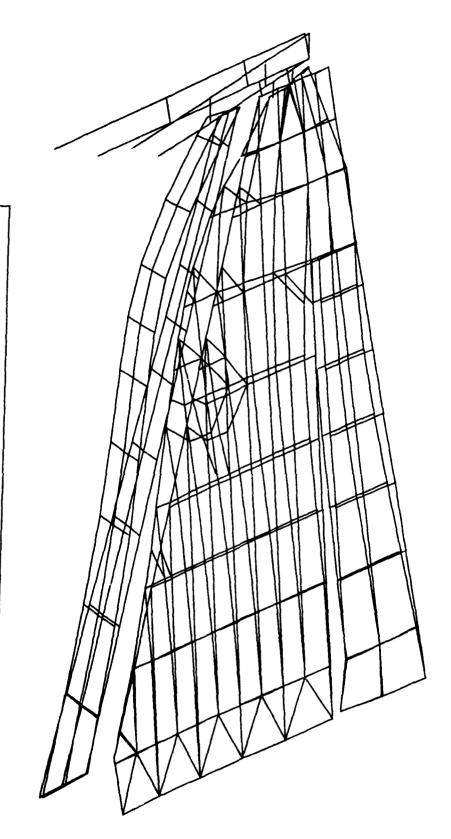
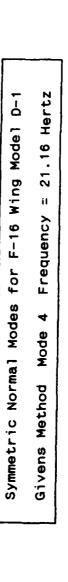


Figure A-7. 1st Torsional Mode (Model D-1)



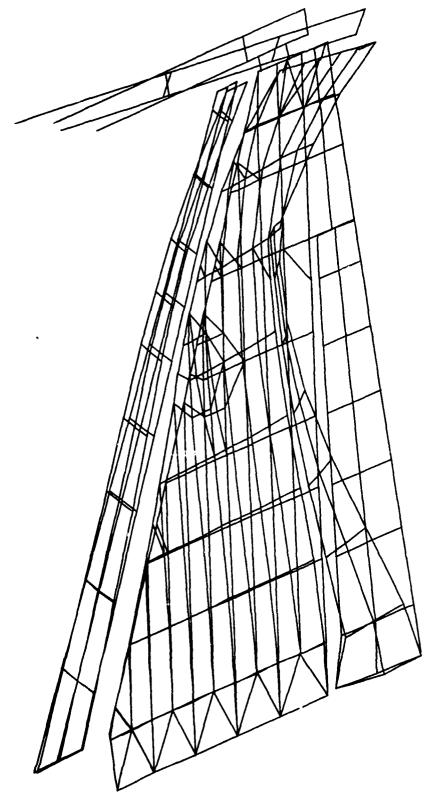


Figure A-8. 2nd Wing Bending Mode (Model D-1)

Symmetric Normal Modes for F-16 Wing Model D-2 Givens Method Mode 1 Frequency = 10.03 Hertz

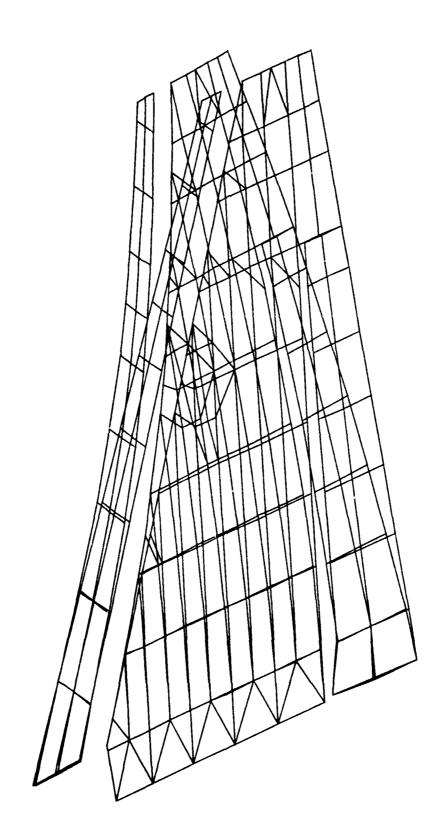


Figure A-9. 1st Wing Bending Mode (Model D-2)

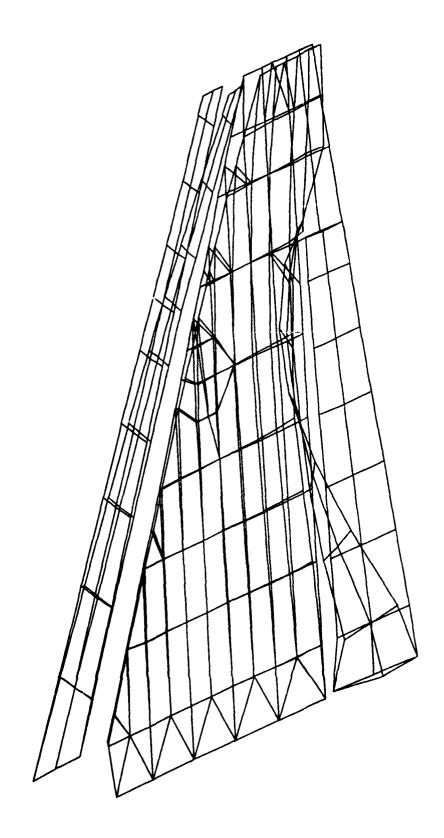


Figure A-10. 2nd Wing Bending Mode (Model D-2)

Symmetric Normal Modes for F-16 Wing Model D-2 Givens Method Mode 3 Frequency = 32.99 Hertz

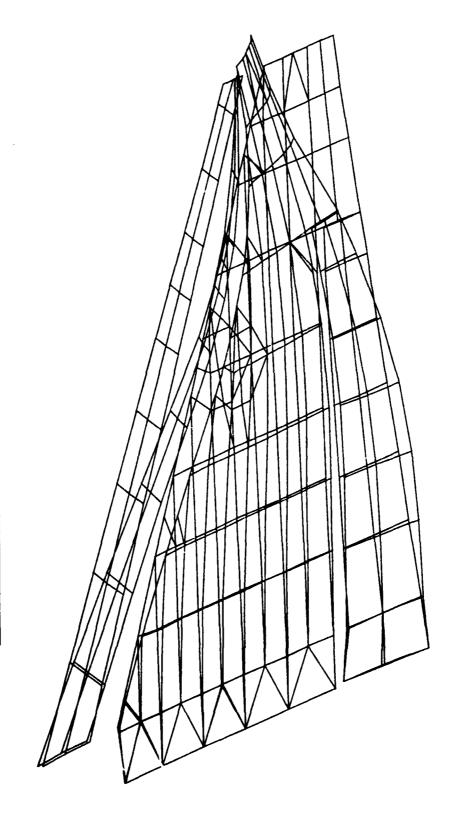


Figure A-11. 1st Torsional Mode (Model D-2)

Symmetric Normal Modes for F-16 Wing Model D-2 Givens Method Mode 4 Frequency = 41.44 Hertz

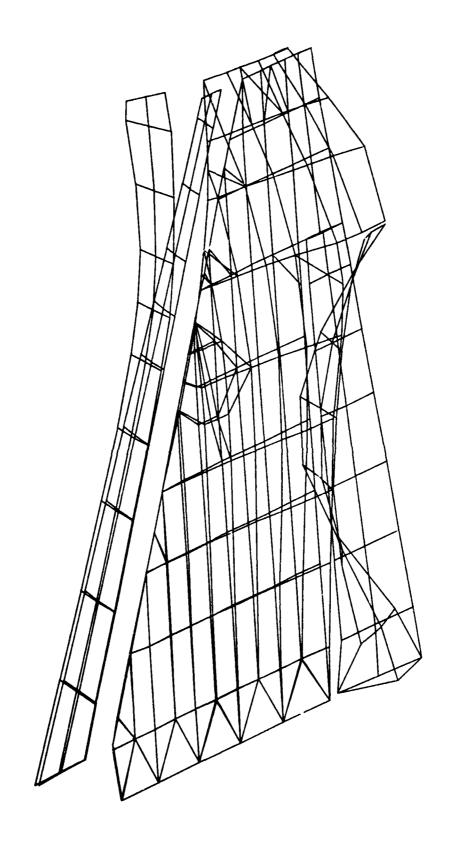


Figure A-12. 2nd Torsional Mode (Model D-2)

Symmetric Normal Modes for F-16 Wing Model D-3 Givens Method Mode 1 Frequency = 10.52 Hertz

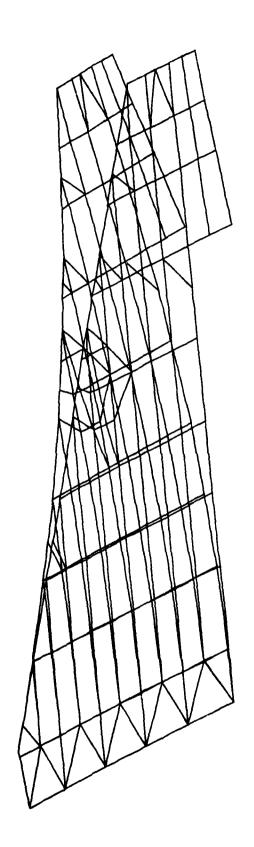


Figure A-13. 1st Wing Bending Mode (Model D-3)

Symmetric Normal Modes for F-16 Wing Model D-3 Givens Method Mode 2 Frequency = 35.29 Hertz

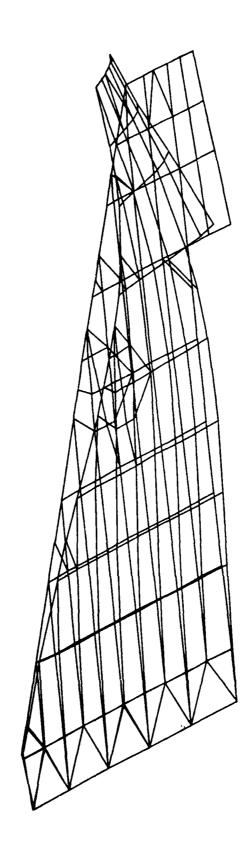


Figure A-14. 2nd Wing Bending Mode (Model D-3)

Symmetric Normal Modes for F-16 Wing Model D-3

Frequency = 45.59 Hertz Mode 3 Givens Method

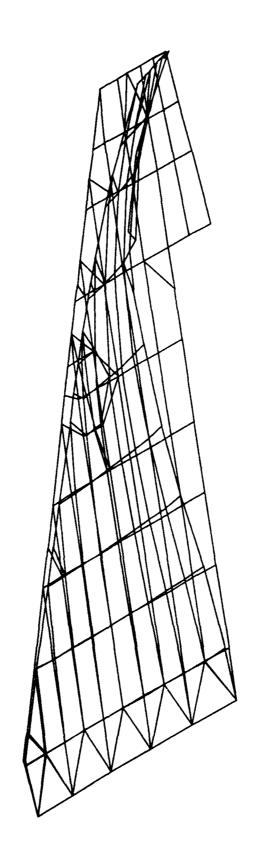


Figure A-15. 1st Torsional Mode (Model D-3)

Symmetric Normal Modes for F-16 Wing Model D-3 Givens Method Mode 4 Frequency = 70.47 Hertz

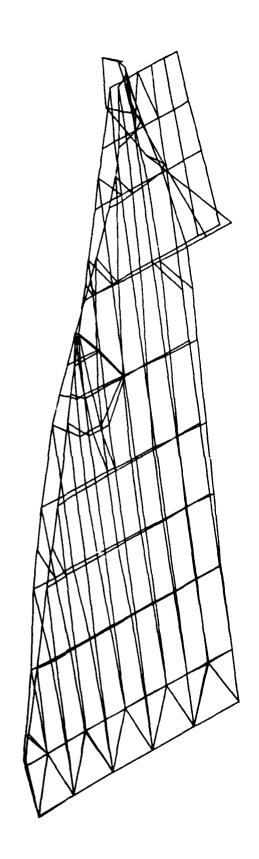


Figure A-16. 2nd Torsional Mode (Model D-3)

Symmetric Normal Modes for F-16 Wing Model D-4 Givens Method Mode 1 Frequency = 10.94 Hertz

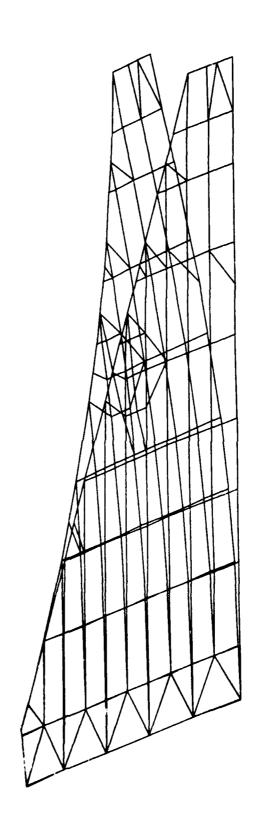
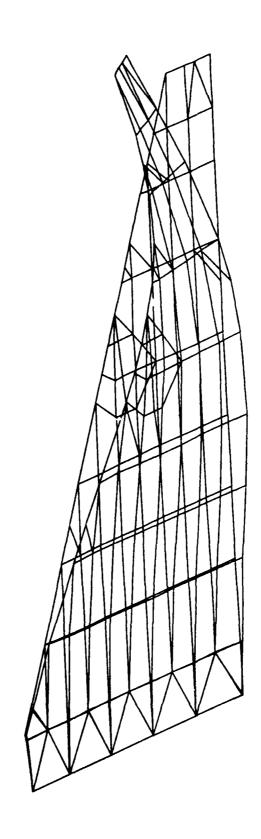


Figure A-17. 1st Wing Bending Mode (Model D-4)

Figure A-18. 2nd Wing Bending Mode (Model D-4)

Symmetric Normal Modes for F-16 Wing Model D-4
Givens Method Mode 2 Frequency = 37.28 Hertz



Symmetric Normal Modes for F-16 Wing Model D-4 Givens Method Mode 3 Frequency = 48.15 Hertz

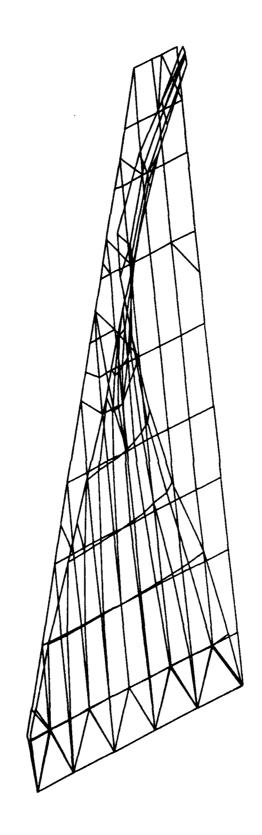
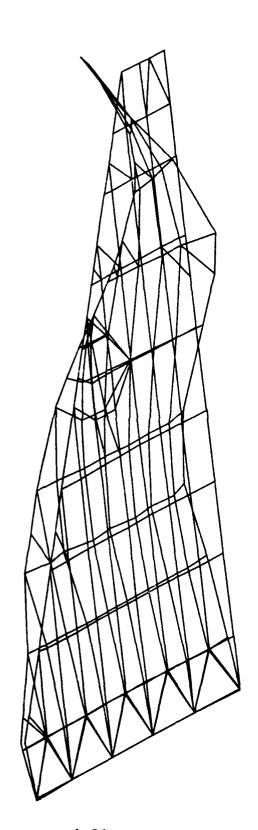


Figure A-19. 1st Torsional Mode (Model D-4)

Figure A-20. 2nd Torsional Mode (Model D-4)

Symmetric Normal Modes for F-16 Wing Model D-4 Givens Method Mode 4 Frequency = 77.67 Hertz



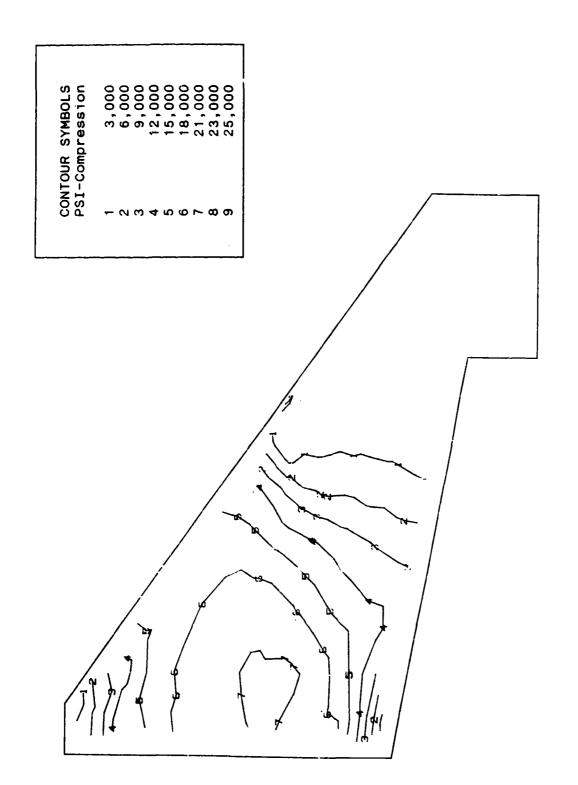
A-21

APPENDIX B

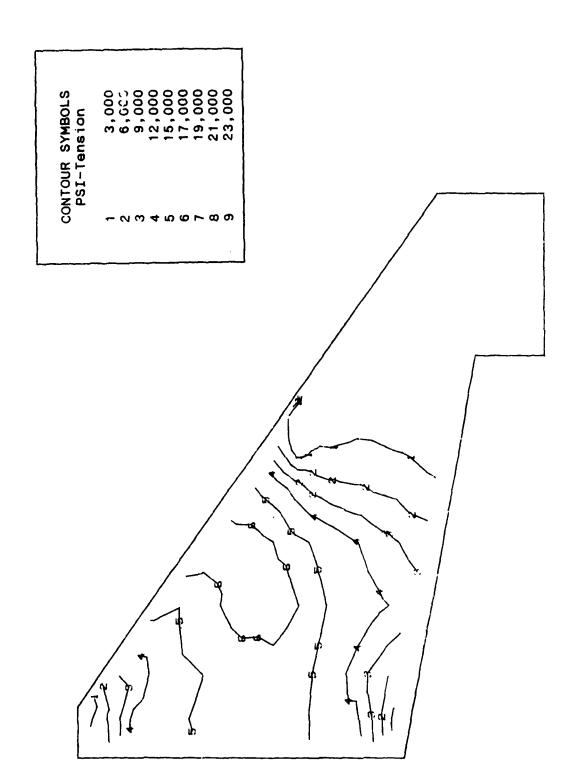
STATIC ANALYSIS OF UNDAMAGED WING MODELS

Figure B-1, Upper Wing Surface (Undamaged Model D-3)

Figure B-2. Lower Wing Surface (Undamaged Model D-3)



Stress Contours on Upper Wing Surface (Undamaged Model D-3) Figure B-3.



Stress Contours on Lower Wing Surface (Undamaged Model D-3) Figure B-4.

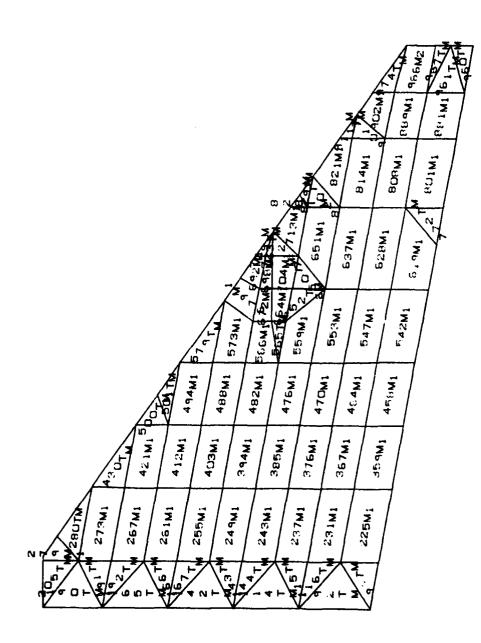
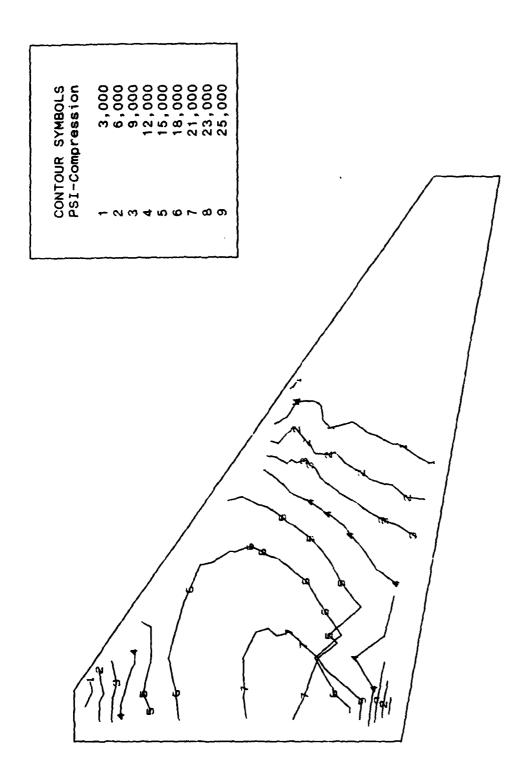
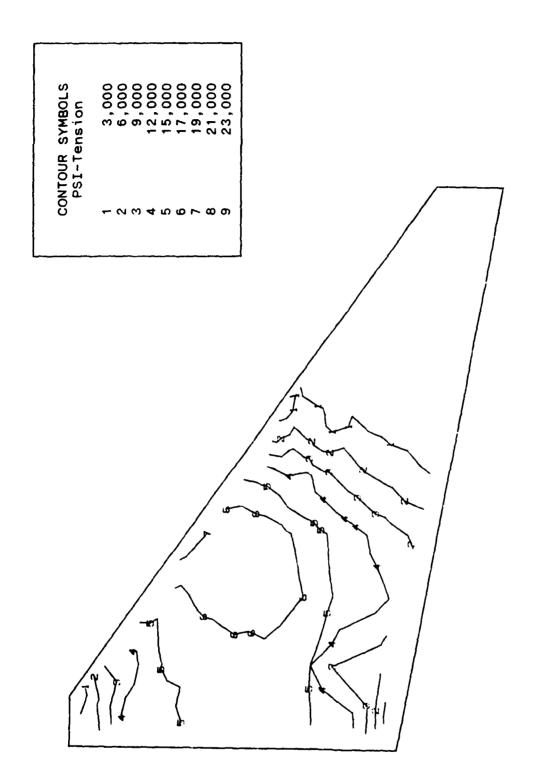


Figure B-5. Upper Wing Surface (Undamaged Model D-4)

Figure B-6. Lower Wing Surface (Undamaged Model D-4)



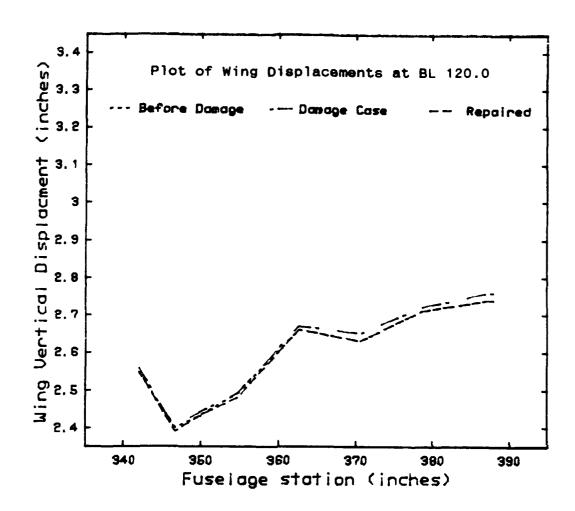
Stress Contours on Upper Wing Surface (Undamaged Model D-4) Figure B-7.



Stress Contours on Lower Wing Surface (Undamaged Model D-4) Figure B-8.

APPENDIX C

ANALYSIS OF DAMAGE CASE #1



Tabulated Displacements Fuselage St. 387.9 378.6 370.6 362.6 354.6 349.7 346.6 341.9 Model D-3 2.74 2.71 2.63 2.66 2.49 2.43 2.40 2.55 Model DC-1 2.76 2.72 2.67 2.49 2.44 2.40 2.65 2.56 Model DC-1R 2.74 2.71 2.63 2.66 2.48 2.39 2.43 2.55

	Comparison Av Disp	of Residual % Change	Strength Torsion mode	% Change
Model D-3	2.58		45.59	
Model DC-1	2.59	-0.4	45.15	-1.0
Model DC-1R	2.58	+0.4	45.62	+1.0

Figure C-1. Summary of Damage Case #1 Results

Figure C-2. Upper Wing Surface (Model DC-1)

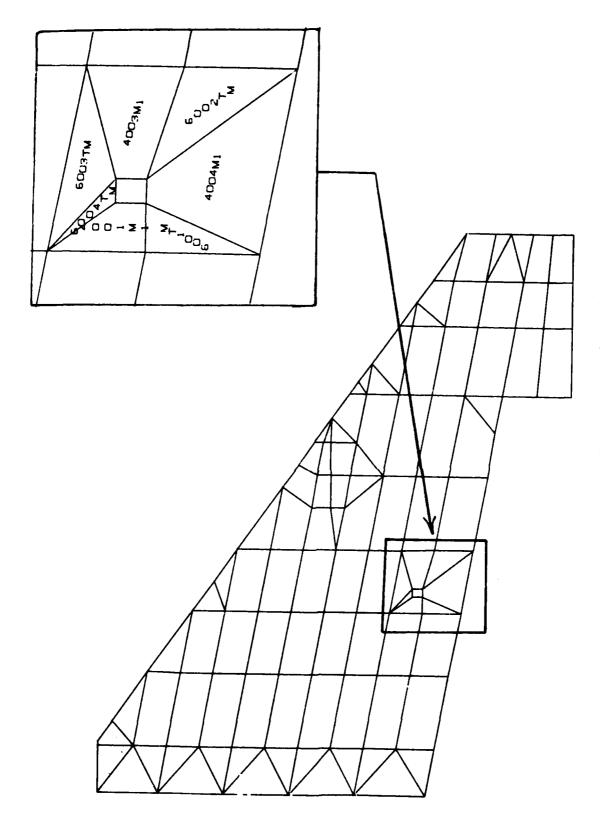
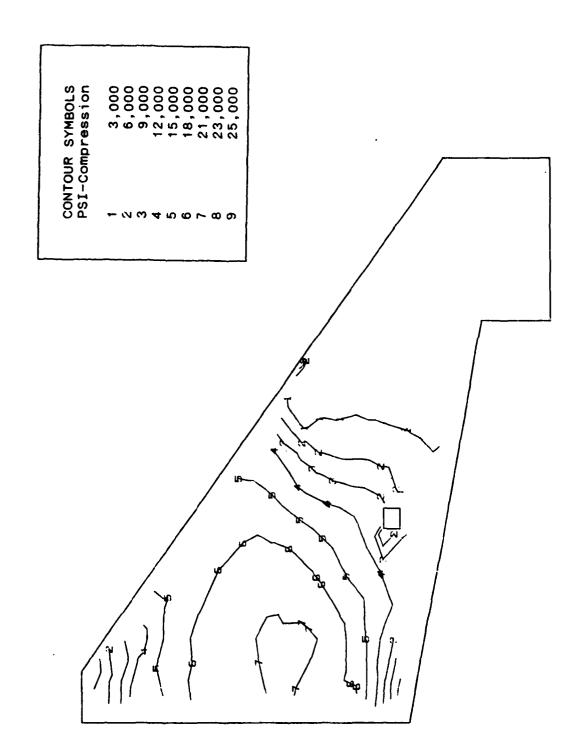
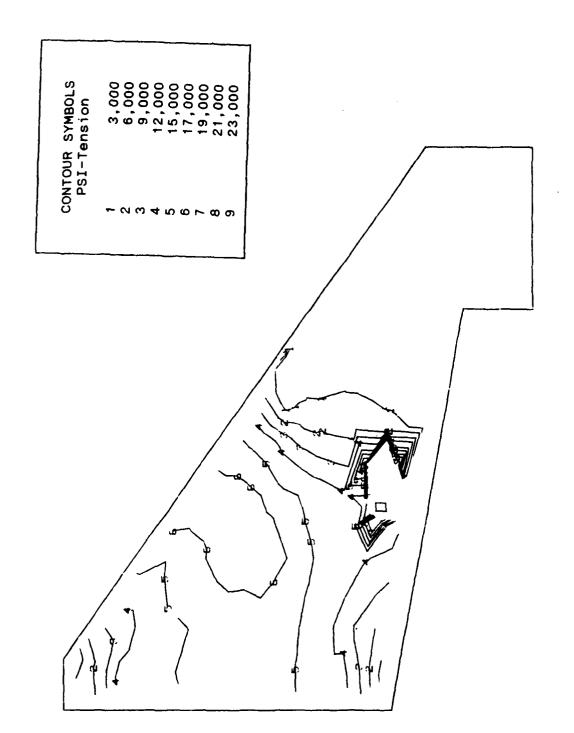


Figure C-3. Lower Wing Surface (Model DC-1)



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Stress Contours on Upper Wing Surface (Model DC-1) Figure C-4.



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Stress Contours on Lower Wing Surface (Model DC-1) Figure C-5.

Symmetric Normal Modes for F-16 Wing Model DC-1 Givens Method Mode 1 Frequency = 10.49 Hertz

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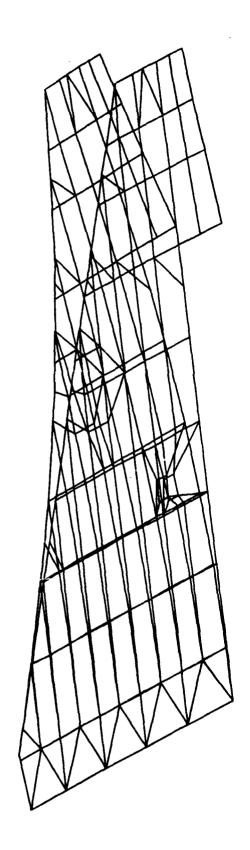


Figure C-6. 1st Wing Bending Mode (Model DC-1)

Symmetric Normal Modes for F-16 Wing Model DC-1 Givens Method Mode 2 Frequency = 35.26 Hertz

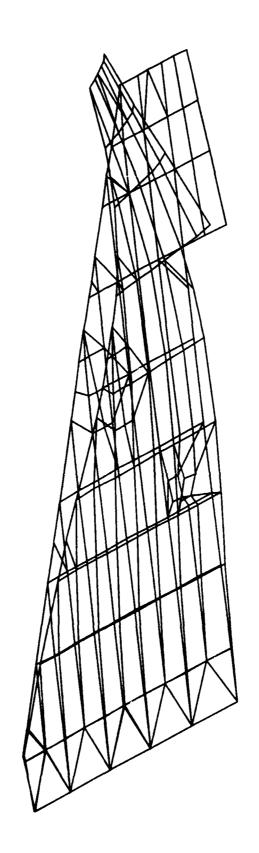


Figure C-7. 2nd Wing Bending Mode (Model DC-1)

Symmetric Normal Modes for F-16 Wing Model DC-1 Givens Method Mode 3 Frequency = 45.15 Hertz

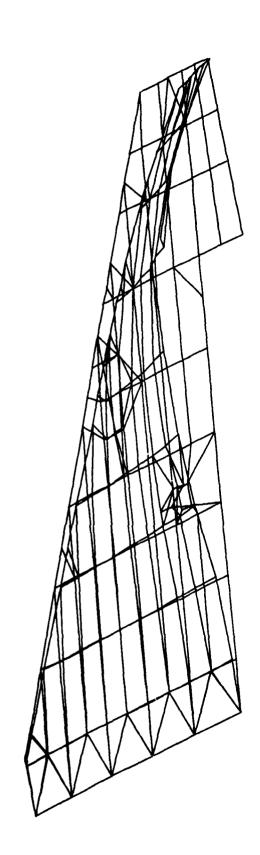


Figure C-8. 1st Torsional Mode (Model DC-1)

Symmetric Normal Modes for F-16 Wing Model DC-1 Givens Method Mode 4 Frequency = 70.21 Hertz

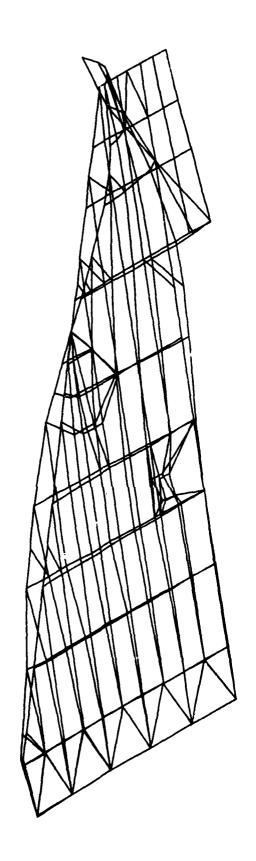


Figure C-9. 2nd Torsional Mode (Model DC-1)

Figure C-10. Upper Wing Surface (Model DC-1R)

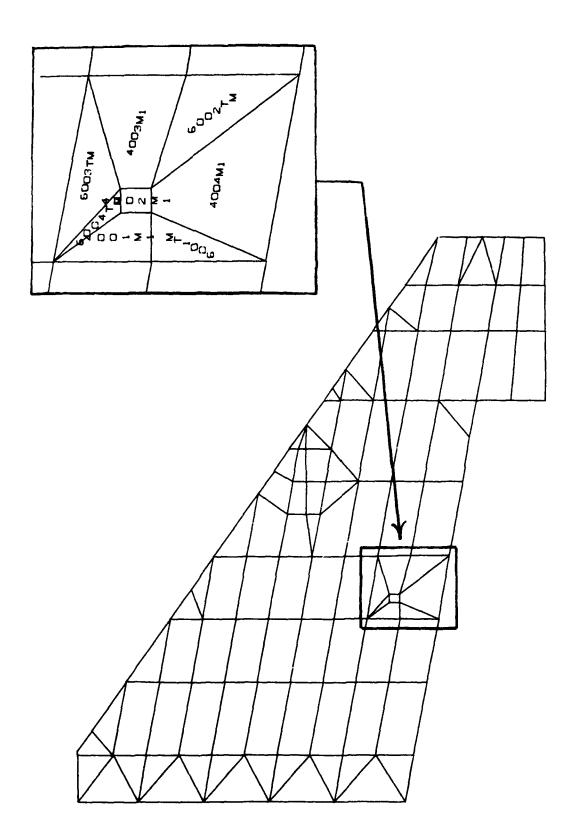
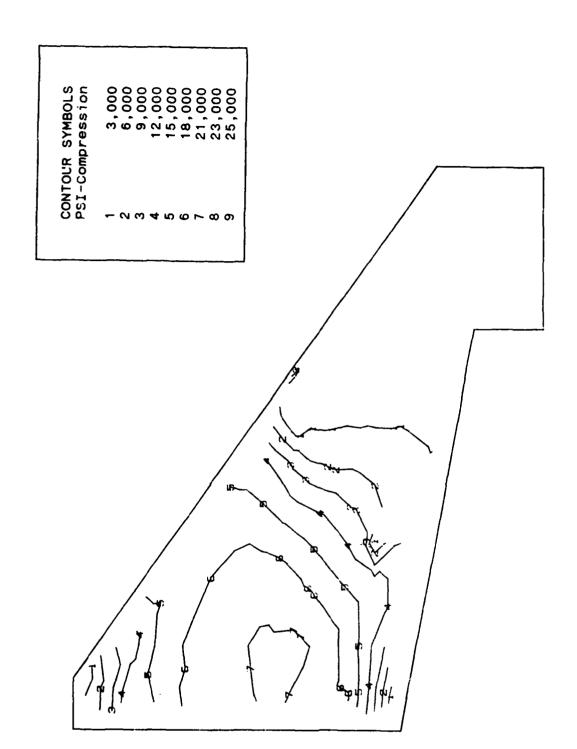
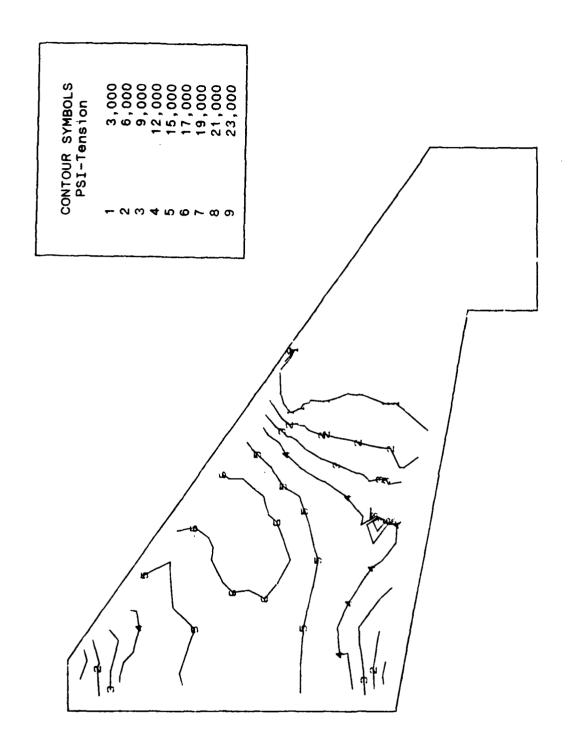


Figure C-11. Lower Wing Surface (Model DC-1R)



Stress Contours on Upper Wing Surface (Model DC-1R) Figure C-12.



Stress Contours on Lower Wing Surface (Model DC-1R) Figure C-13.

C-14

e e e e an original. An original Symmetric Normal Modes for F-16 Wing Model DC-1R Givens Method Mode 1 Frequency = 10.54 Hertz

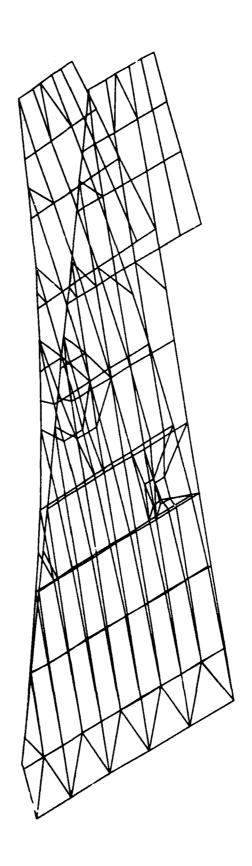


Figure C-14. 1st Wing Bending Mode (Model DC-1R)

Symmetric Normal Modes for F-16 Wing Model DC-1R Givens Method Mode 2 Frequency = 35.28 Hertz

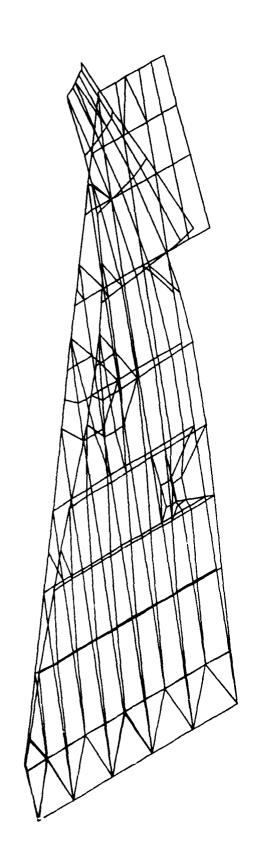


Figura C-15. 2nd Wing Bending Mode (Model DC-1R)

Symmetric Normal Modes for F-16 Wing Model DC-1R Givens Method Mode 3 Frequency = 45.62 Hertz

Figure C-16. 1st Torsional Mode (Model DC-1R)

Symmetric Normal Modes for F-16 Wing Model DC-1R Givens Method Mode 4 Frequency = 70.48 Hertz

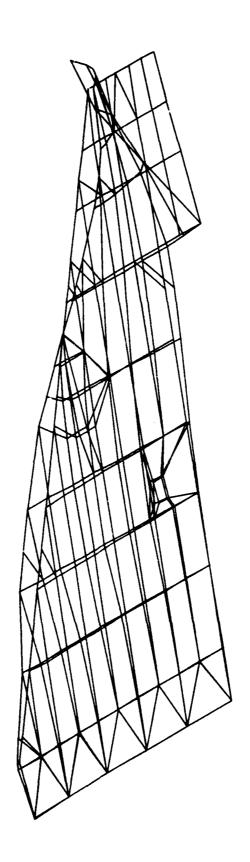
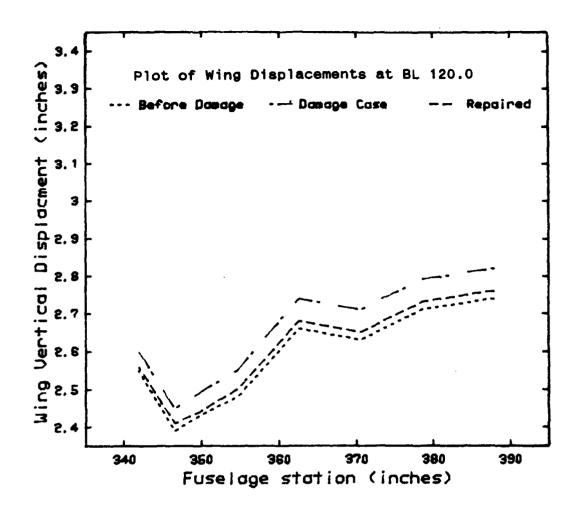


Figure C-17. 2nd Torsional Mode (Model DC-1R)

APPENDIX D

ANALYSIS OF DAMAGE CASE #2



Tabulated Displacements 387.9 378.6 370.6 362.6 354.6 349.7 346.6 341.9 Fuselage St. 2.39 2.55 2.43 2.71 2.63 2.66 2.48 2.74 Model DC-1R 2.60 2.45 2.55 2.49 2.71 2.74 2.82 2.79 Model DC-2 2.56 2.41 2.50 2.44 2.65 2.68 2.76 2.73 Model DC-2R

	Comparison Av Disp	of Residual % Change	Torsion mode	* Change
Model D-1R Model DC-2 Model DC-2R	2.58 2.64 2.59	-2.3 +1.9	45.62 44.75 45.56	-1.9 +1.8

Figure D-1. Summary of Damage Case #2 Results

Figure D-2. Upper Wing Surface (Model DC-2)

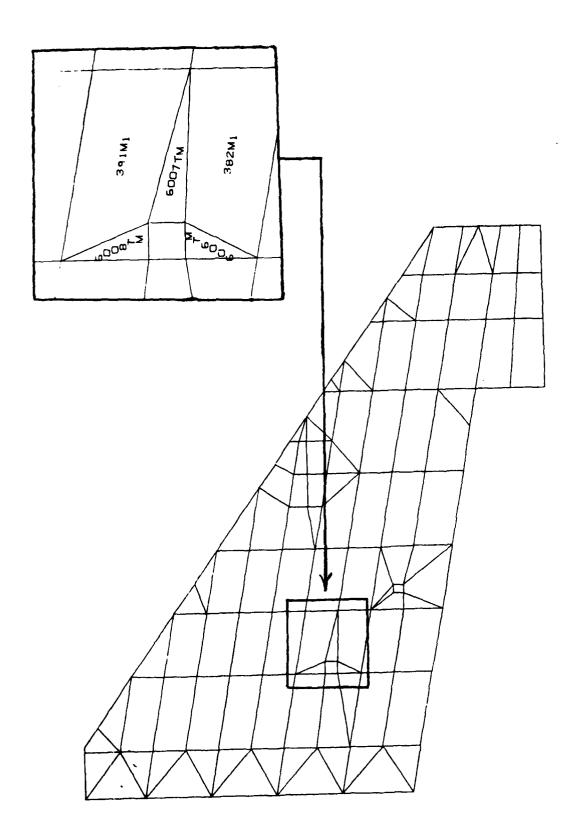
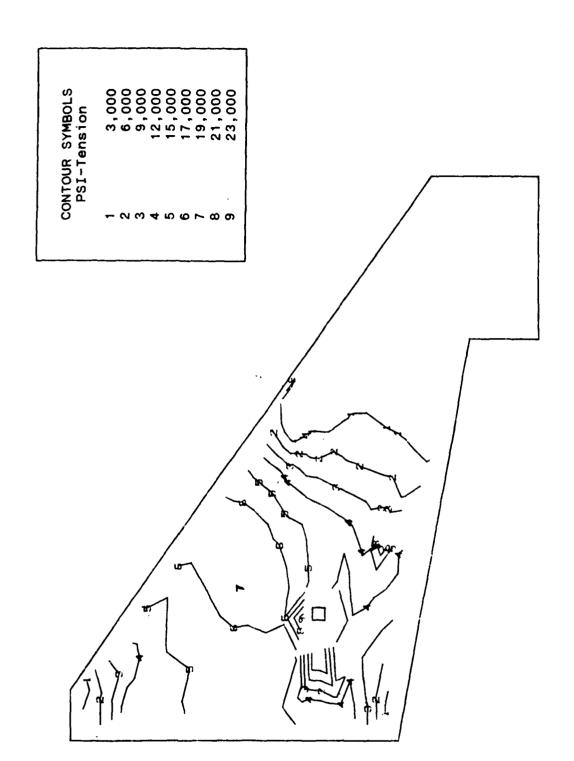


Figure D-3. Lower Wing Surface (Model DC-2)

Stress Contours on Upper Wing Surface (Model DC-2) Figure D-4.



Stress Contours on Lower Wing Surface (Model DC-2) Figure D-5.

Symmetric Normal Modes for F-16 Wing Model DC-2 Givens Method Mode 1 Frequency = 10.45 Hertz

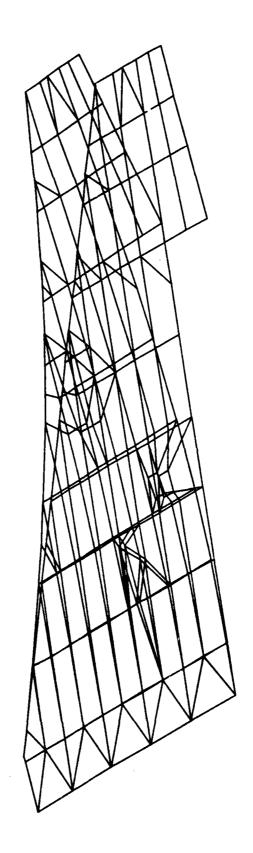


Figure D-6. 1st Wing Bending Mode (Model DC-2)

Symmetric Normal Modes for F-16 Wing Model DC-2 Givens Method Mode 2 Frequency = 34.94 Hertz

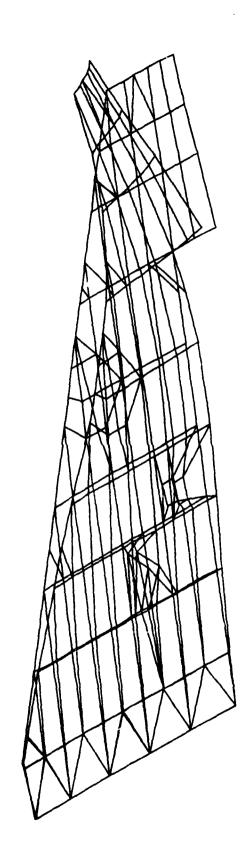


Figure D-7. 2nd Wing Bending Mode (Model DC-2)

Symmetric Normal Modes for F-16 Wing Model DC-2 Givens Method Mode 3 Frequency = 44.75 Hertz

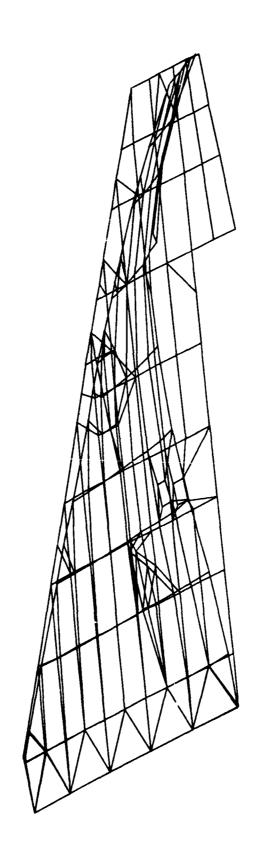


Figure D-8. 1st Torsional Mode (Model DC-2)

Symmetric Normal Modes for F-16 Wing Model DC-2 Givens Method Mode 4 Frequency = 66.75 Hertz

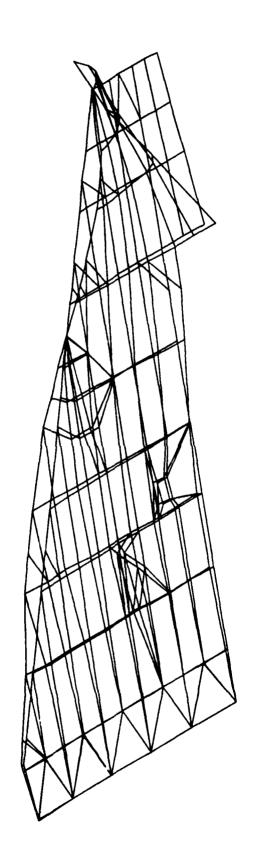


Figure D-9. 2nd Torsional Mode (Model DC-2)

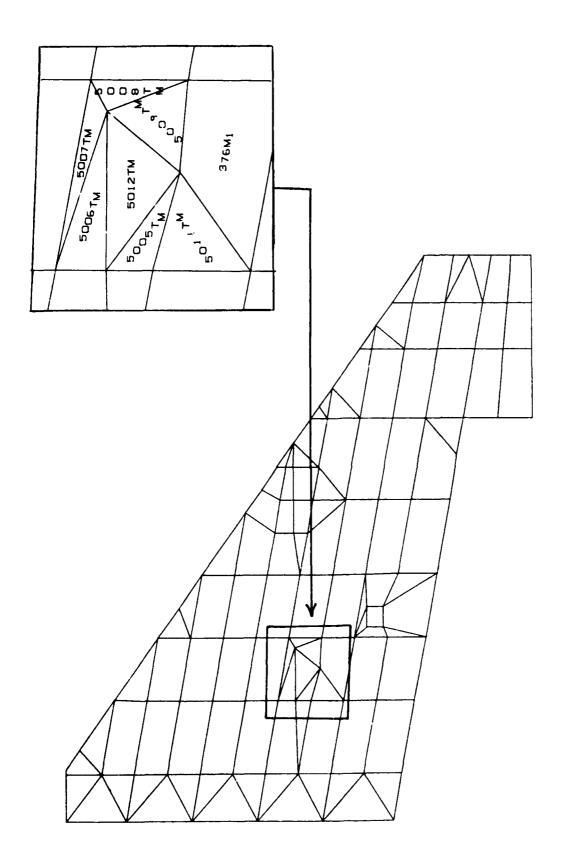
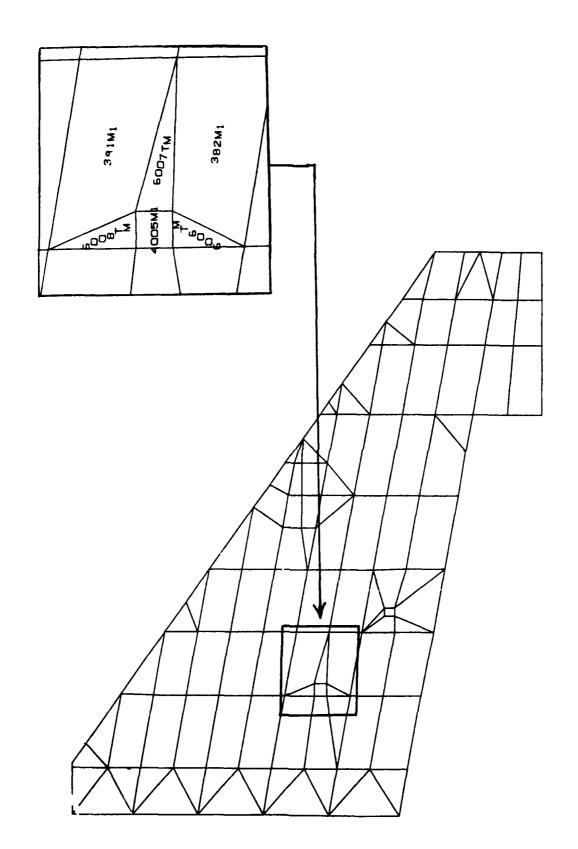
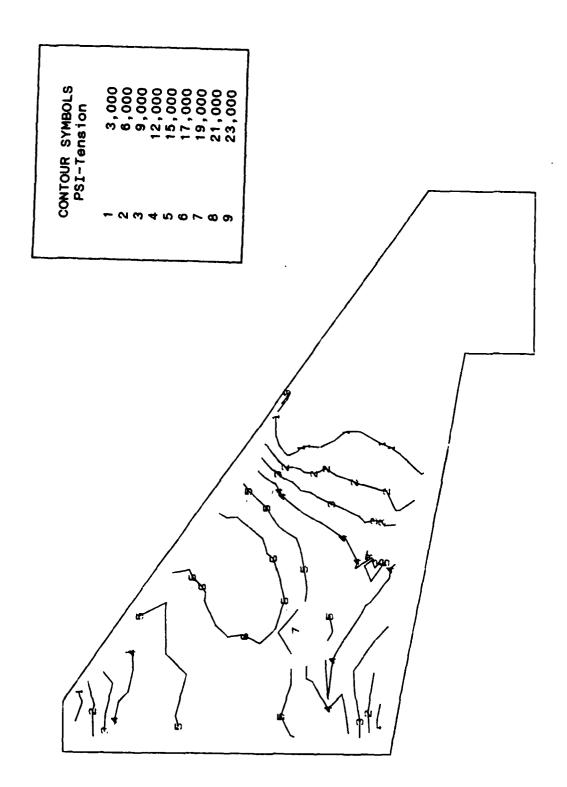


Figure D-10. Upper Wing Surface (Model DC-2R)



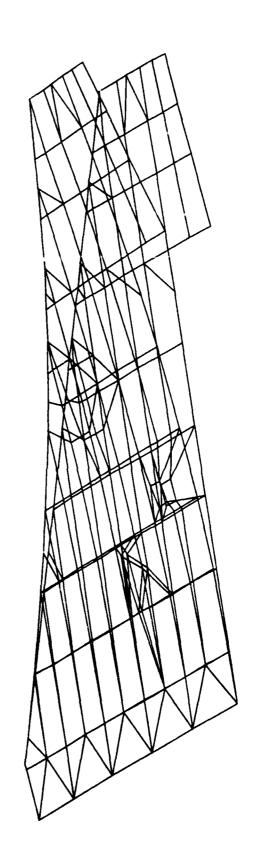
D-12

Stress Contours on Upper Wing Surface (Model DC-2R) Figure D-12.



Stress Contours on Lower Wing Surface (Model DC-2R) Figure D-13.

Symmetric Normal Modes for F-16 Wing Model DC-2R Givens Method Mode 1 Frequency = 10.55 Hertz



Symmetric Normal Modes for F-16 Wing Model DC-2R Givens Method Mode 2 Frequency = 35.05 Hertz

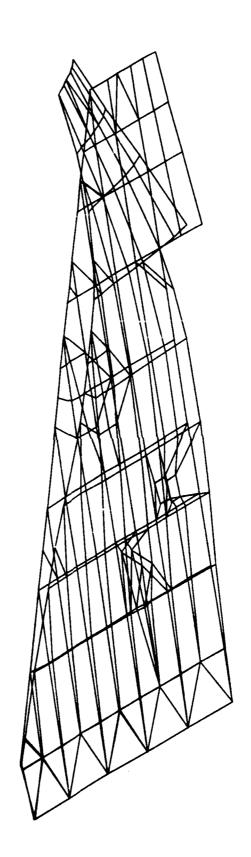


Figure D-15. 2nd Wing Bending Mode (Model DC-2R)

Symmetric Normal Modes for F-16 Wing Model DC-2R Givens Method Mode 3 Frequency = 45.56 Hertz

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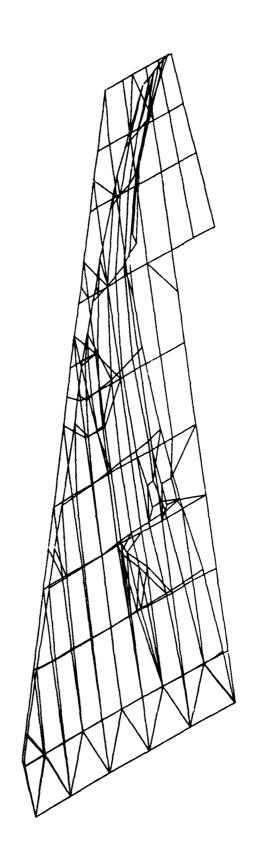


Figure D-16. 1st Torsional Mode (Model DC-2R)

Symmetric Normal Modes for F-16 Wing Model DC-2R Givens Method Mode 4 Frequency = 70.38 Hertz

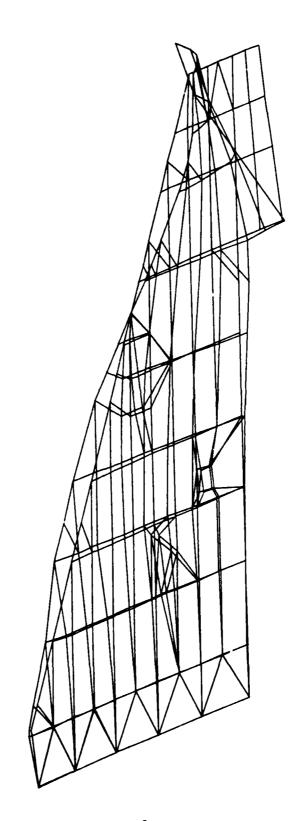
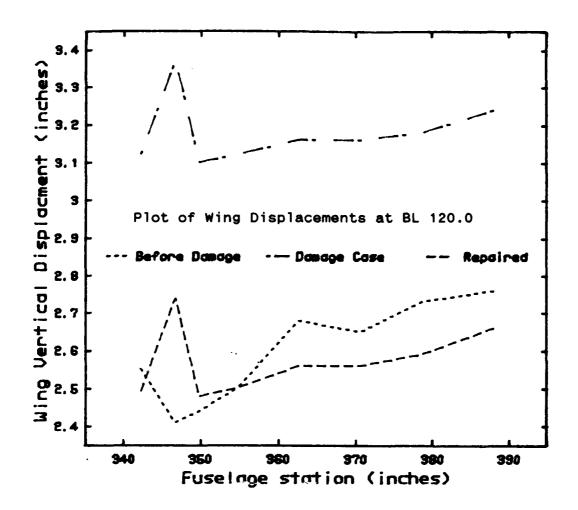


Figure D-17. 2nd Torsional Mode (Model DC-2R)

APPENDIX E

ANALYSIS OF DAMAGE CASE #3



Tabulated Displacements Fuselage St. 387.9 378.6 370.6 352.6 354.6 349.7 346.6 341.9 Model DC-2R 2.76 2.73 2.65 2.68 2.50 2.44 2.41 2.56 Model DC-3 3.24 3.18 3.16 3.16 3.12 3.10 3.37 3.11 Model DC-3R 2.66 2.59 2.56 2.56 2.50 2.48 2.74 2.48

	Comparison Av Disp	of Residual % Change	Strength Torsion mode	% Change
Model D-2R	2.59		45.56	
Model DC-3	3.18	-22.8	29.64	-34.9
Model DC-3R	2.57	+23.6	47.02	+38.1

Figure E-1. Summary of Damage Case #3 Results

Figure E-2. Upper Wing Surface (Model DC-3)

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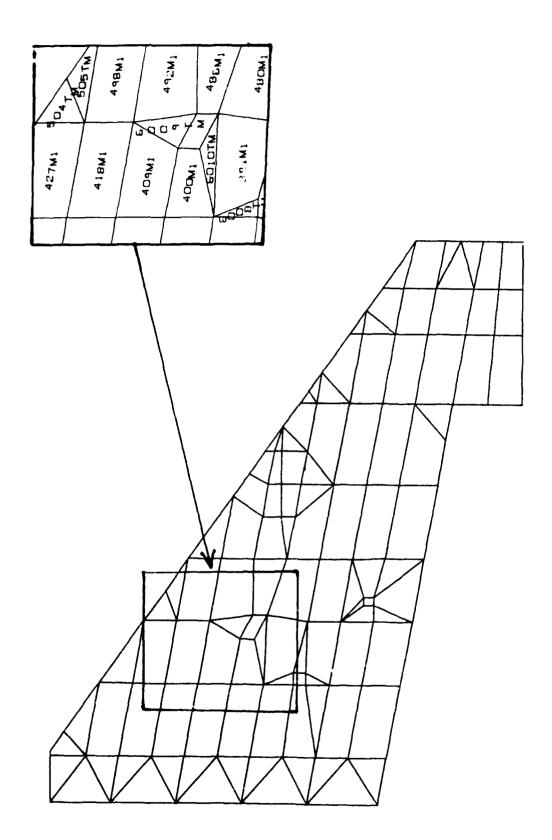
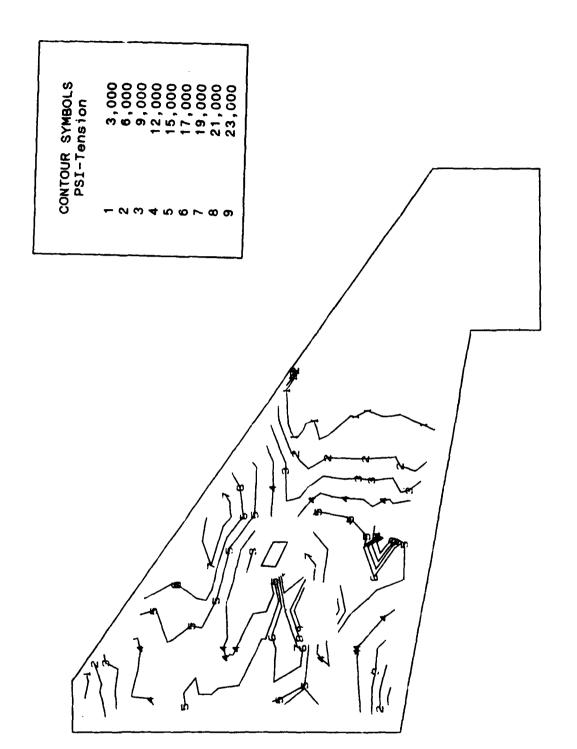


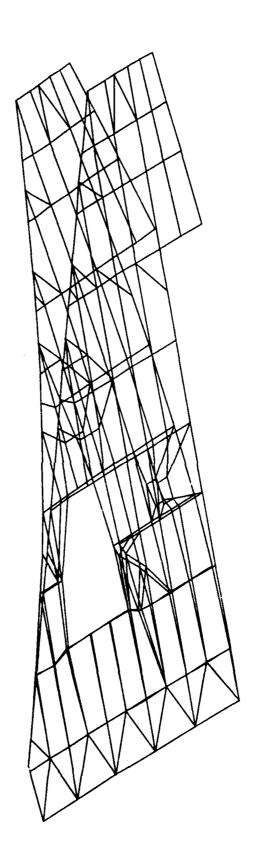
Figure E-3. Lower Wing Surface (Model DC-3)

Stress Contours on Upper Wing Surface (Model DC-3) Figure E-4.



Stress Contours on Lower Wing Surface (Model DC-3) Figure E-5.

Symmetric Normal Modes for F-16 Wing Model DC-3 Givens Method Mode 1 Frequency = 9.54 Hertz



Symmetric Normal Modes for F-16 Wing Model DC-3 Givens Method Mode 3 Frequency = 38.11 Hertz

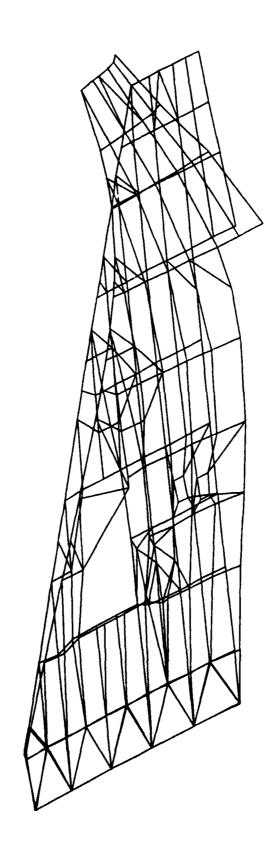
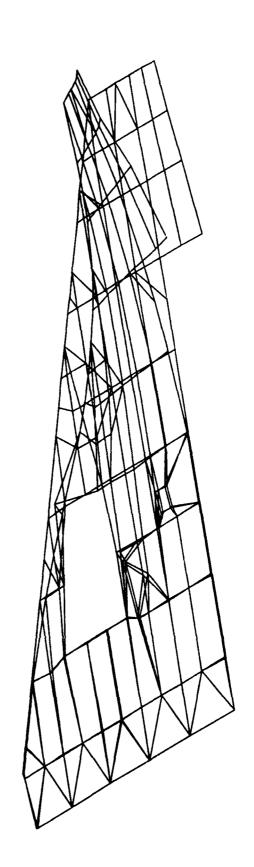


Figure E-7. 2nd Wing Bending Mode (Model DC-3)

Symmetric Normal Modes for F-16 Wing Model DC-3 Givens Method Mode 2 Frequency = 29.64 Hertz



Symmetric Normal Modes for F-16 Wing Model DC-3
Givens Method Mode 4 Frequency = 47.23 Hertz

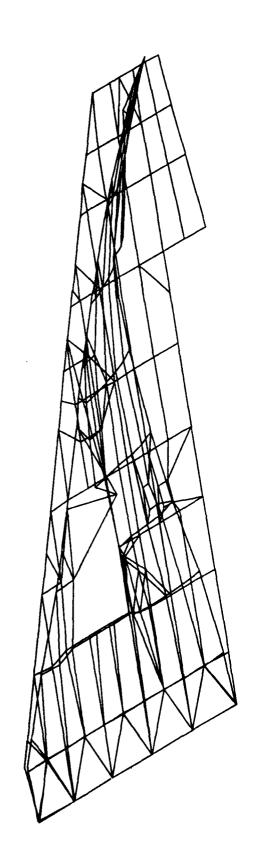
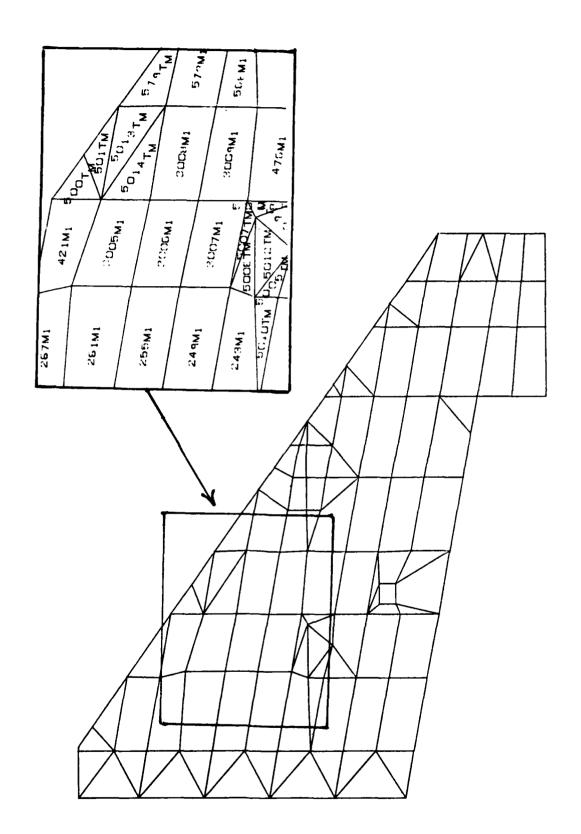


Figure E-9. 2nd Torsional Mode (Model DC-3)



E-11

Figure E-11. Lower Wing Surface (Model DC-3R)

Stress Contours on Uppar Wing Surface (Model DC-3R) Figure E-12.

Stress Contours on Lower Wing Surface (Model DC-3R) Figure E-13.

Symmetric Normal Modes for F-16 Wing Model DC-3R Givens Method Mode 1 Frequency = 10.54 Hertz

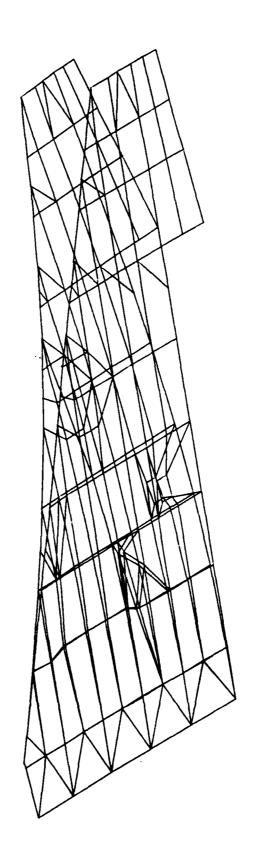


Figure E-14. 1st Wing Bending Mode (Model DC-3R)

Symmetric Normal Modes for F-16 Wing Model DC-3R Givens Method Mode 2 Frequency = 35.23 Hertz

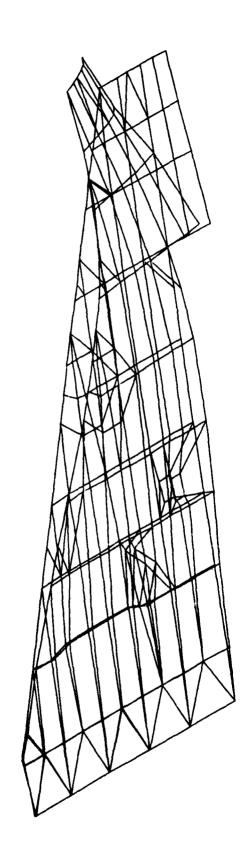


Figure E-15. 2nd Wing Bending Mode (Model DC-3R)

Symmetric Normal Modes for F-16 Wing Model DC-3R Givens Method Mode 3 Frequency = 47.02 Hertz

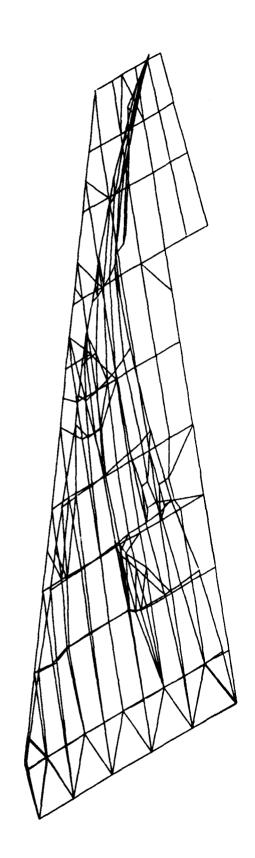


Figure E-16. 1st Torsional Mode (Model DC-3R)

Symmetric Normal Modes for F-16 Wing Model DC-3R Givens Method Mode 4 Frequency = 70.67 Hertz

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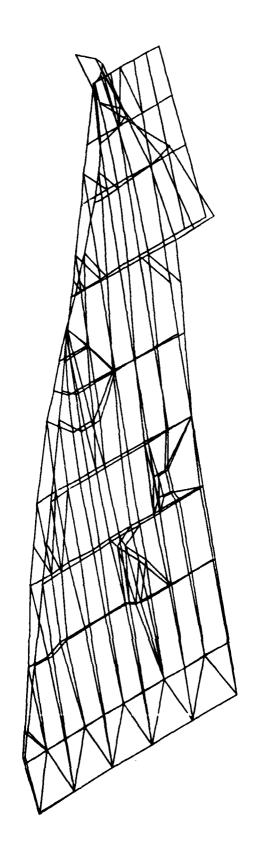
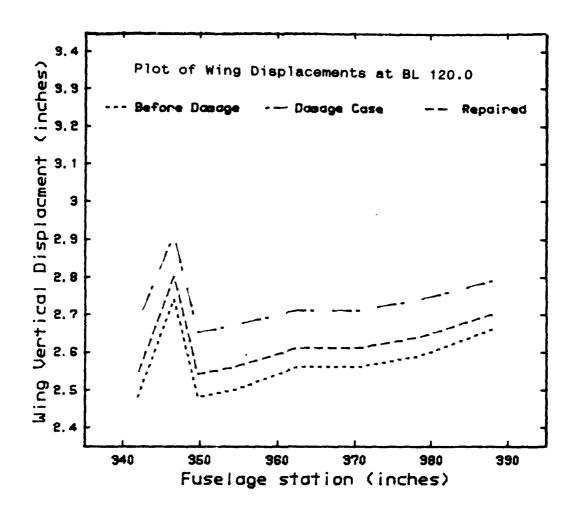


Figure E-17. 2nd Torsional Mode (Model DC-3R)

APPENDIX F

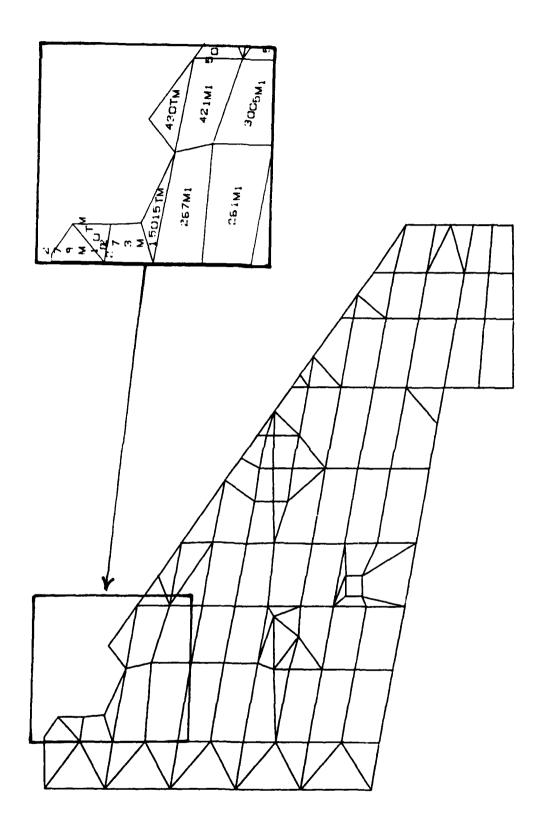
ANALYSIS OF DAMAGE CASE #4



Tabulated Displacements 387.9 378.6 370.6 362.6 354.6 349.7 346.6 341.9 Fuselage St. 2.74 2.48 Model DC-3R 2.59 2.56 2.56 2.50 2.48 2.66 2.71 2.91 2.68 2.74 2.71 2.67 2.65 Model DC-4 2.79 2.64 Model DC-4R 2.70 2.61 2.61 2.56 2.54 2.80 2.54

		Comparison Av Disp	of Residual % Change	Strength Torsion mode	% Change
Mode 1	D-3R	2.57		47.02	
Mode 1	DC-4	2.73	-6.2	46.22	-1.7
Mode ?	DC-4R	2.63	+3.9	46.93	+1.5

Figure F-1. Summary of Damage Case #4 Results



F-3

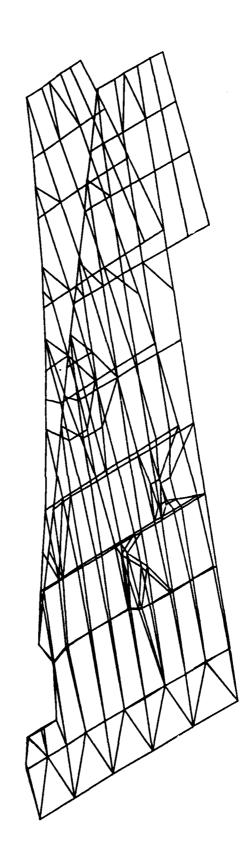
Figure F-3. Lower Wing Surface (Model DC-4)

F-4

Figure F-4. Stress Contours on Upper Wing Surface (Model DC-4)

Stress Contours on Lower Wing Surface (Model DC-4) Figure F-5.

Symmetric Normal Modes for F-16 Wing Model DC-4
Givens Method Mode 1 Frequency = 10.33 Hertz



Symmetric Normal Modes for F-16 Wing Model DC-4 Givens Method Mode 2 Frequency = 34.64 Hertz

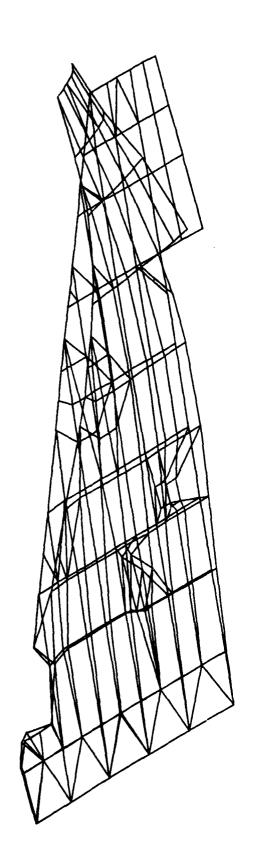
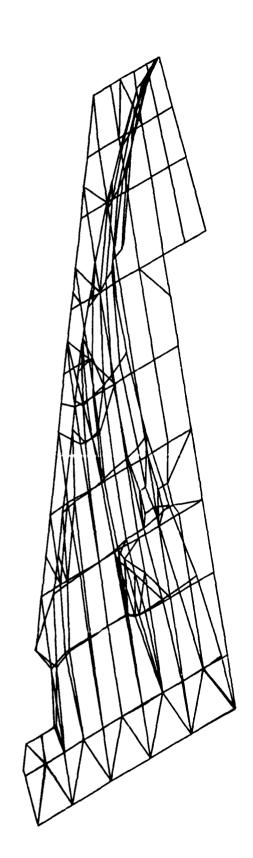


Figure F-7. 2nd Wing Bending Mode (Model DC-4)

Figure F-8. 1st Torsional Mode (Model DC-4)

Symmetric Normal Modes for F-16 Wing Model DC-4 Givens Method Mode 3 Frequency = 46.22 Hertz



Symmetric Normal Modes for F-16 Wing Model DC-4 Givens Method Mode 4 Frequency = 68.04 Hertz

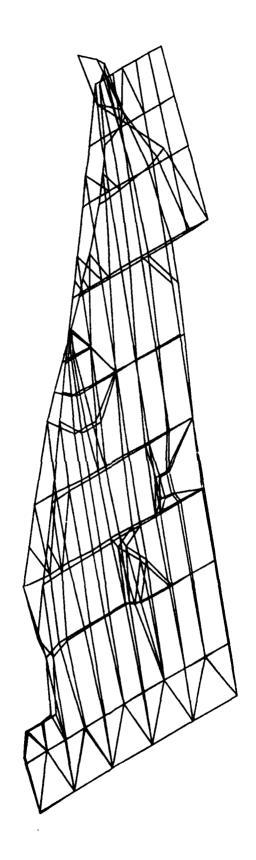


Figure F-9. 2nd Torsional Mode (Model DC-4)

Figure F-10. Upper Wing Surface (Model DC-4R)

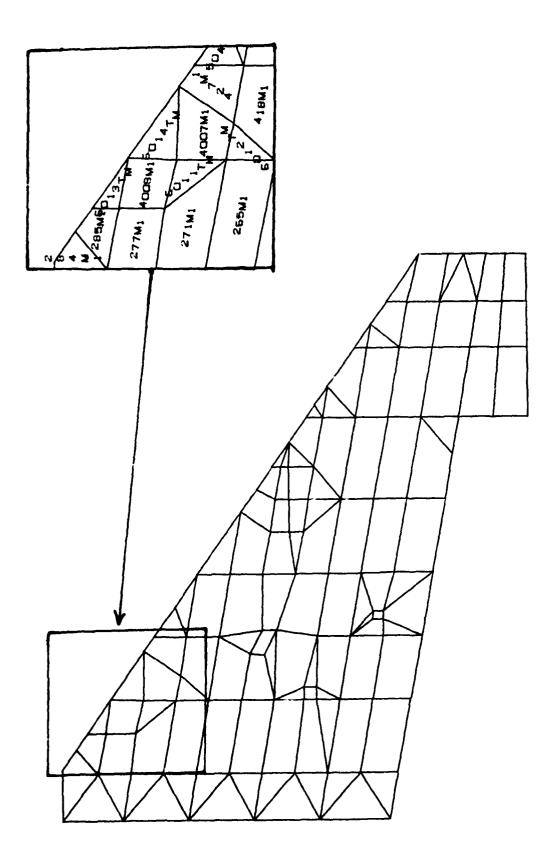
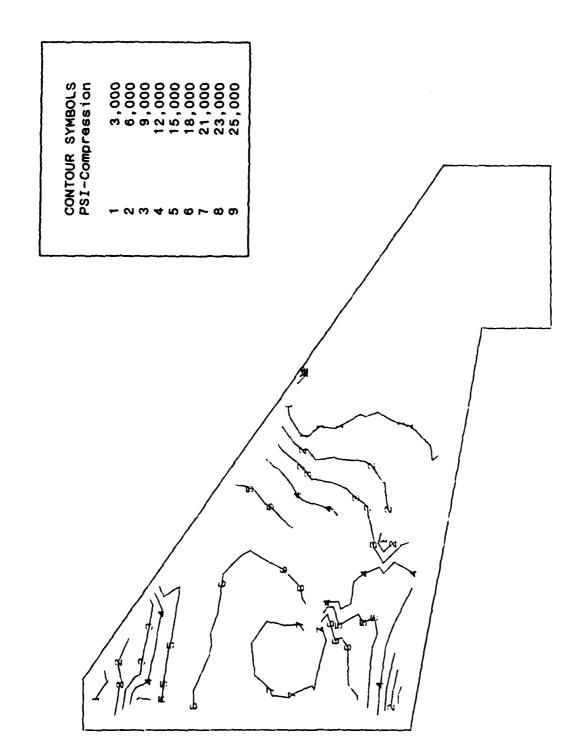
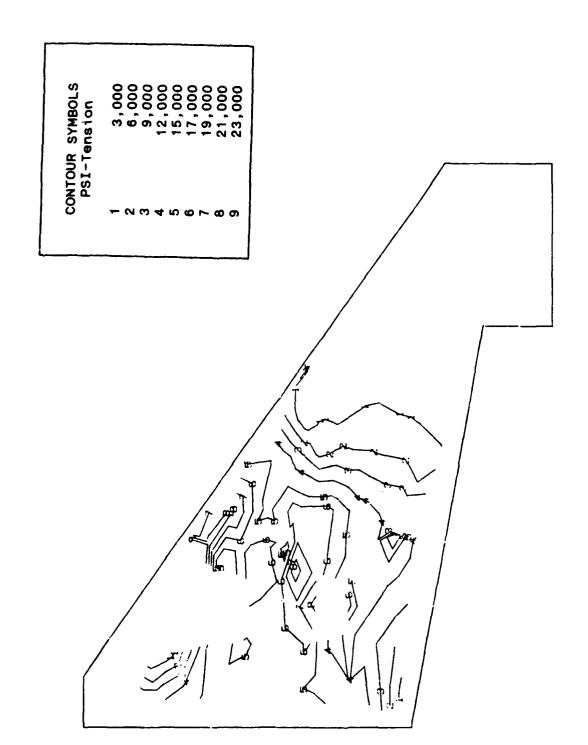


Figure F-11. Lower Wing Surface (Model DC-4R)



Stress Contours on Upper Wing Surface (Model DC-4R) Figure F-12.



Stress Contours on Lower Wing Surface (Model DC-4R) Figure F-13.

F-14

Symmetric Normal Modes for F-16 Wing Model DC-4R Givens Method Mode 1 Frequency = 10.47 Hertz

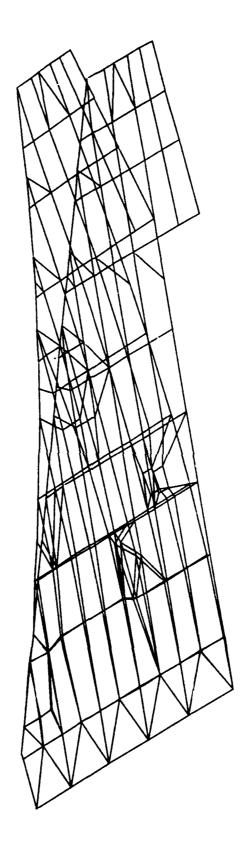


Figure F-14. 1st Wing Bending Mode (Model DC-4R)

Symmetric Normal Modes for F-16 Wing Model DC-4R Givens Method Mode 2 Frequency = 35.06 Hertz

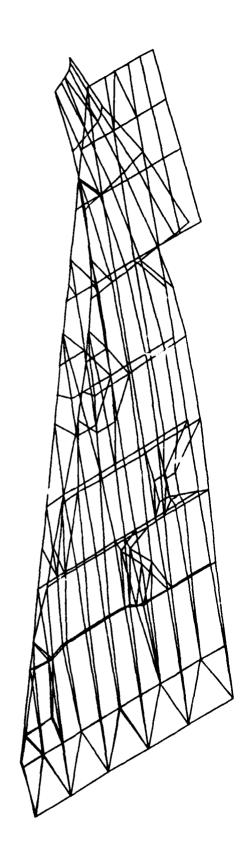


Figure F-15. 2nd Wing Bending Mode (Model DC-4R)

Symmetric Normal Modes for F-16 Wing Model DC-4R Givens Method Mode 3 Frequency = 46.93 Hertz

Figure F-16. 1st Torsional Mode (Model DC-4R)

Symmetric Normal Modes for F-16 Wing Model DC-4R Givens Method Mode 4 Frequency = 70.42 Hertz

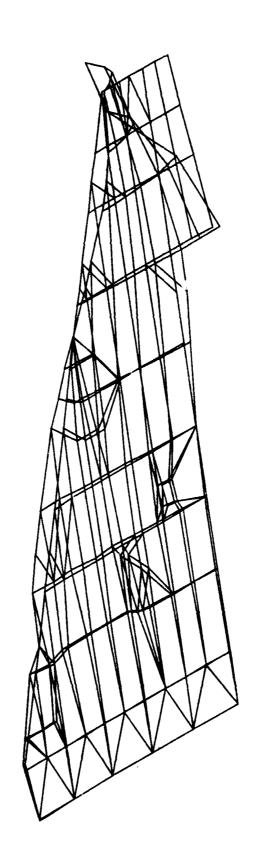
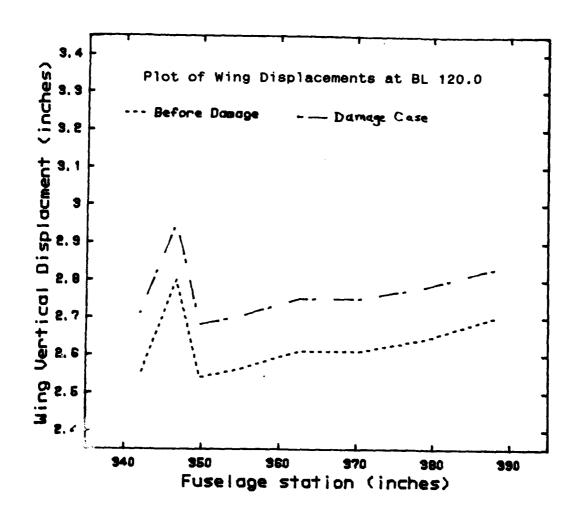


Figure F-17. 2nd Torsional Mode (Model DC-4R)

APPENDIX G

ANALYSIS OF DAMAGE CASE #7



Tabulated Displacements Fuselage St. 387.9 378.6 370.6 362.6 354.6 349.7 346.6 341.9 Model DC-4R 2.70 2.64 2.61 2.61 2.56 2.54 2.80 2.54 Model DC-7 2.78 2.75 2.83 2.75 2.70 2.68 2.95 2.71 Comparison of Residual Strength Av Disp * Change Torsion mode % Change Model D-4R 2.63 46.93 Model DC-7 2.77 -5.3 46.04 -1.9

Figure G-1. Summary of Damage Case #7 Results

Figure G-2. Upper Wing Surface (Model DC-7)

Figure G-3. Lower Wing Surface (Model DC-7)

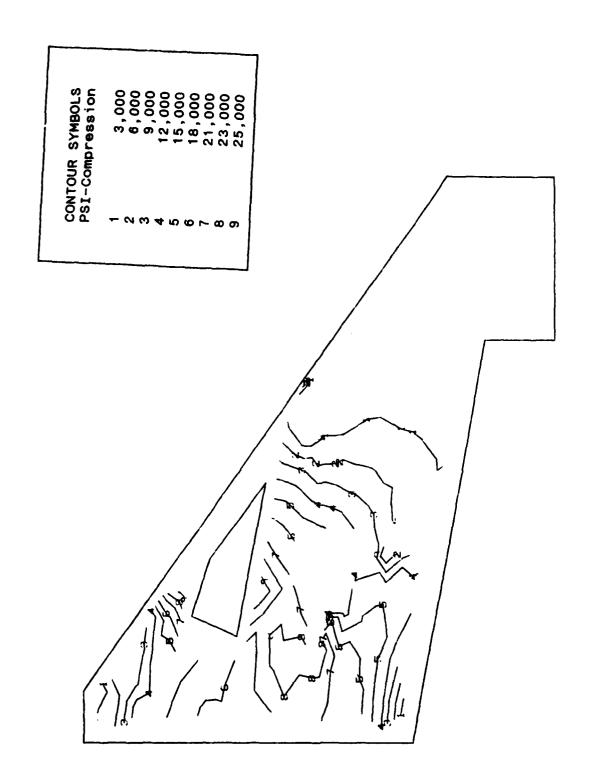
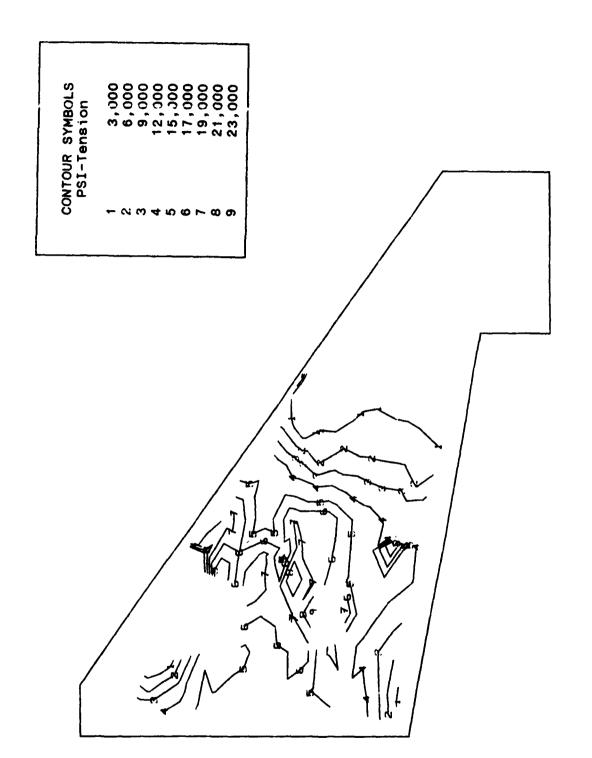


Figure G-4. Stress Contours on Upper Wing Surface (Model DC-7)



Stress Contours on Lower Wing Surface (Model DC-7) Figure G-5,

Symmetric Normal Modes for F-16 Wing Model DC-7 Givens Method Mode 1 Frequency = 10.24 Hertz

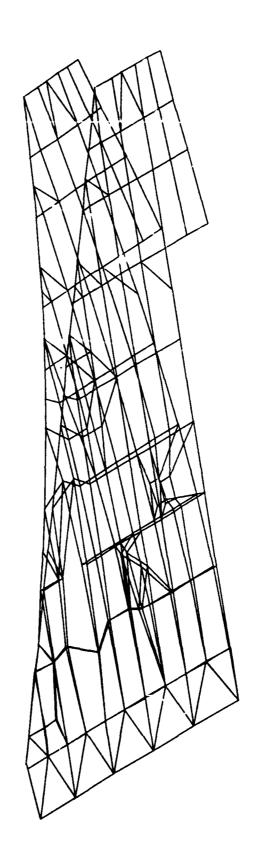


Figure G-6. 1st Wing Bending Mode (Model DC-7)

Symmetric Normal Modes for F-16 Wing Model DC-7 Givens Method Mode 2 Frequency = 34.61 Hertz

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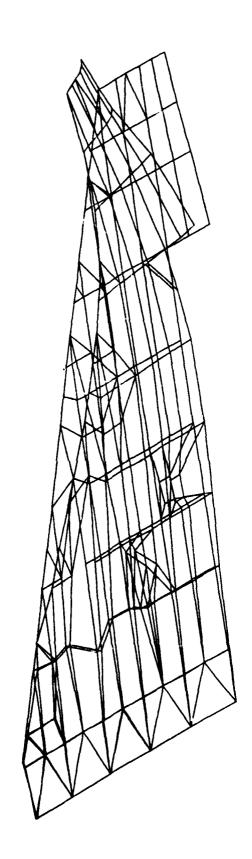


Figure G-7. 2nd Wing Bending Mode (Model DC-7)

Symmetric Normal Modes for F-16 Wing Model DC-7 Givens Method Mode 3 Frequency = 46.04 Hertz

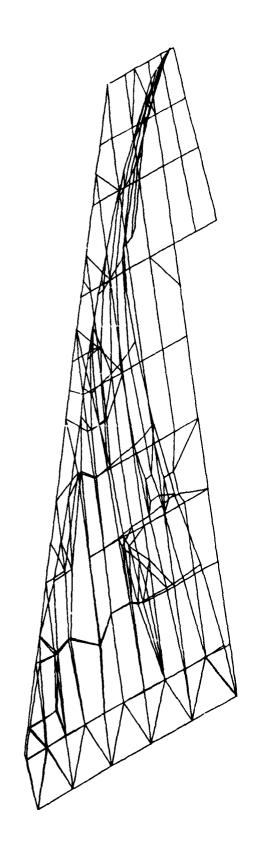


Figure G-8. 1st Torsional Mode (Model DC-7)

Symmetric Normal Modes for F-16 Wing Model DC-7 Givens Method Mode 4 Frequency = 67.33 Hertz

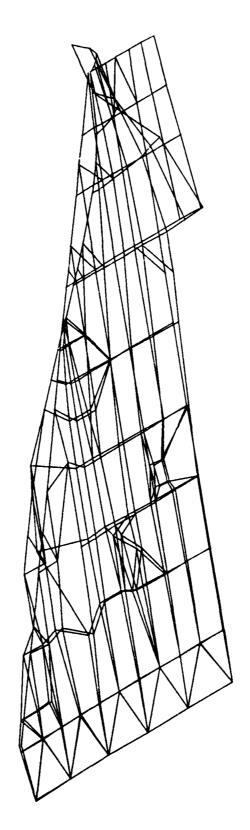
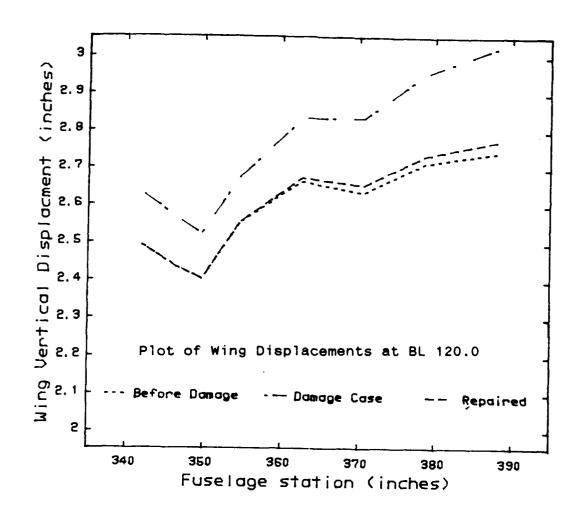


Figure G-9. 2nd Torsional Mode (Model DC-7)

APPENDIX H

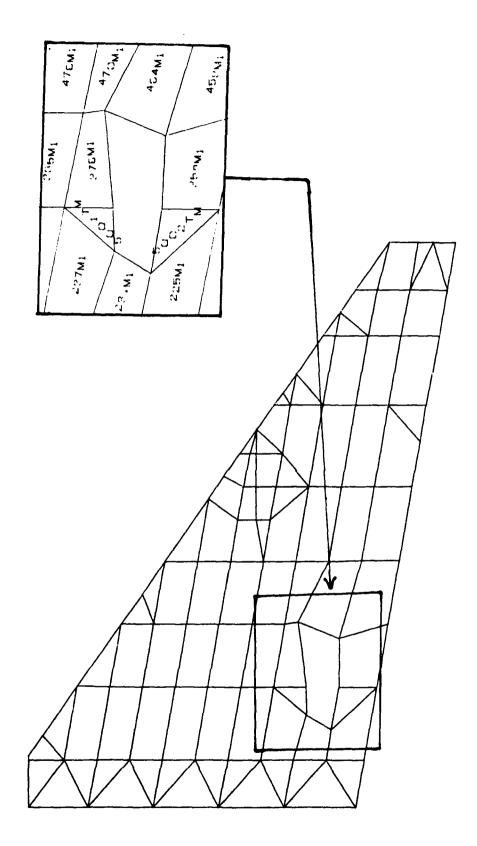
ANALYSIS OF DAMAGE CASE #9



Tabulated Displacements Fuselage St. 387.9 378.6 370.6 362.6 354.6 349.7 346.6 341.9 Model D-4 2.74 2.71 2.63 2.66 2.55 2.40 2.43 2.49 Model DC-9 2.52 2.56 3.02 2.95 2.83 2.83 2.67 2.63 Model DC-9R 2.77 2.73 2.65 2.55 2.40 2.43 2.67 2.49

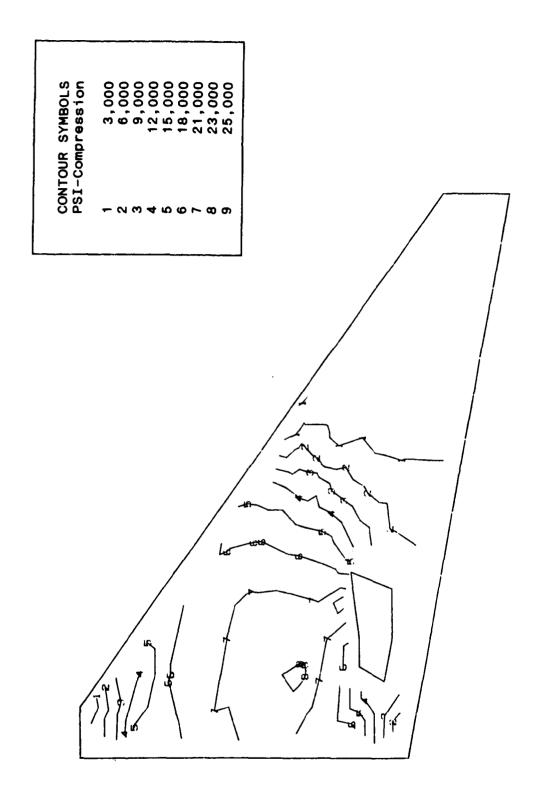
	Comparison Av Disp	of Residual % Change	Torsion mode	% Change		
Model D-4	2.58		48.15	!		
Model DC-9	2.75	-6.6	35.02	-27.3		
Model DC-9R	2.59	+6.2	45.67	+21.9		

Figure H-1. Summary of Damage Case #9 Results

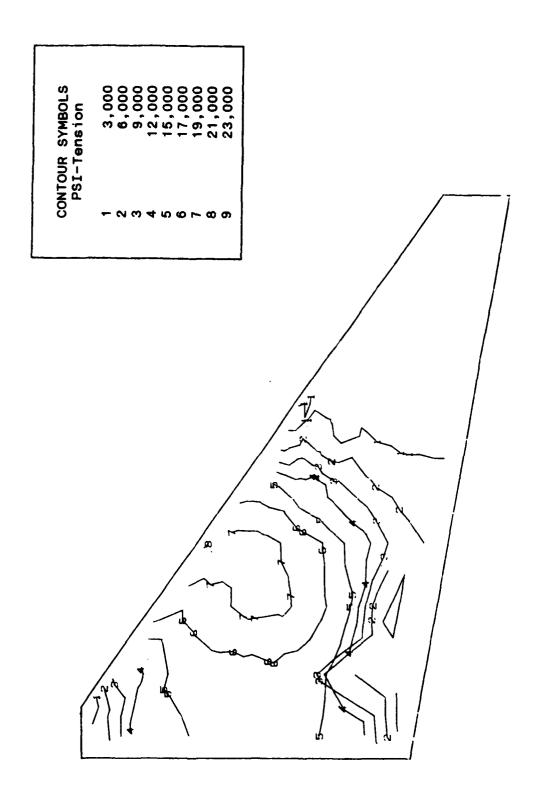


H-3

Figure H-3. Lower Wing Surface (Model DC-9)



Stress Contours on Upper Wing Surface (Model DC-9) Figure H-4.



Stress Contours on Lower Wing Surface (Model DC-9) Figure H-5.

Symmetric Normal Modes for F-16 Wing Model DC-9 Givens Method Mode 1 Frequency = 10.42 Hertz

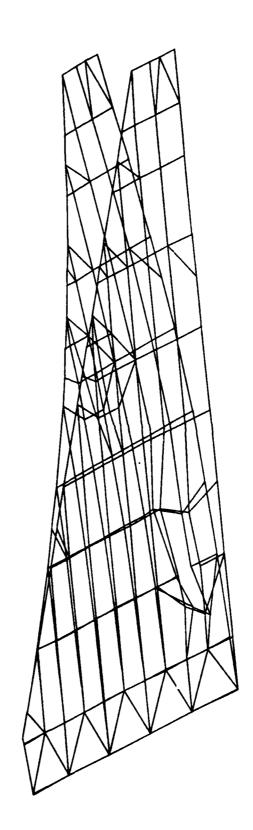


Figure H-6. 1st Wing Bending Mode (Model DC-9)

Symmetric Normal Modes for F-16 Wing Model DC-9 Givens Method Mode 2 Frequency = 31.60 Hertz

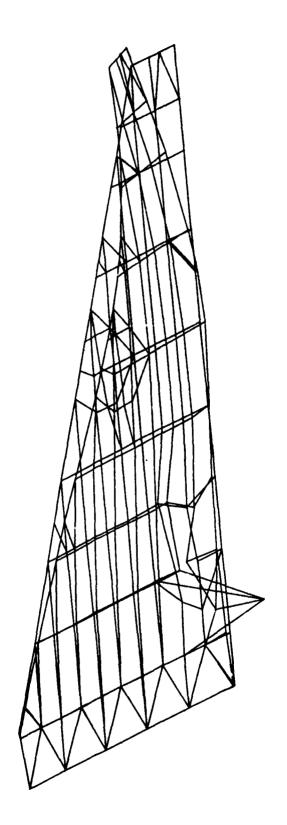


Figure H-7. 2nd Wing Bending Mode (Model DC-9)

Symmetric Normal Modes for F-16 Wing Model DC-9 Givens Method Mode 3 Frequency = 35.02 Hertz

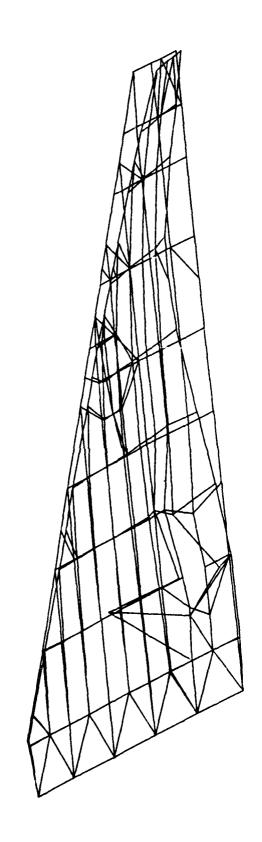


Figure H-8. 1st Torsional Mode (Model DC-9)

Symmetric Normal Modes for F-16 Wing Model DC-9 Givens Method Mode 4 Frequency = 48.06 Hertz

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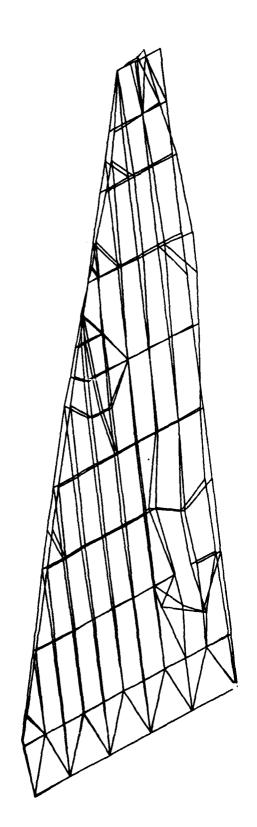


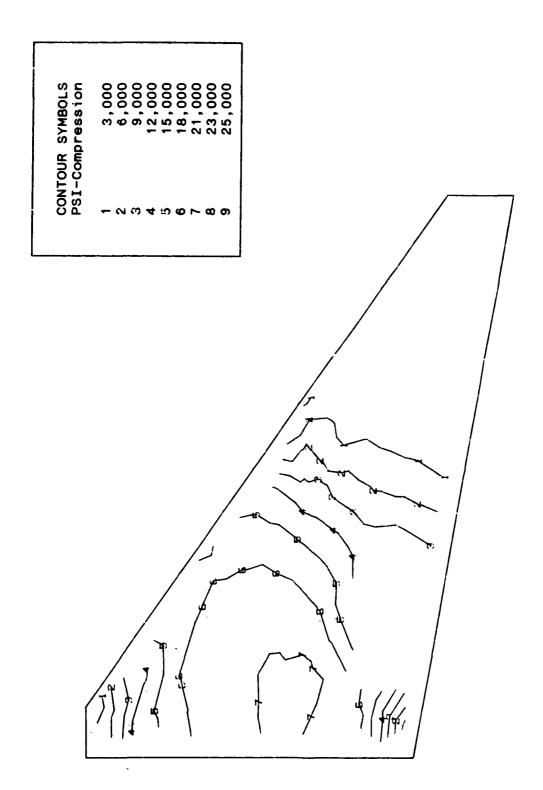
Figure H-9. 2nd Torsional Mode (Model DC-9)

Figure H-10. Upper Wing Surface (Model DC-9R)

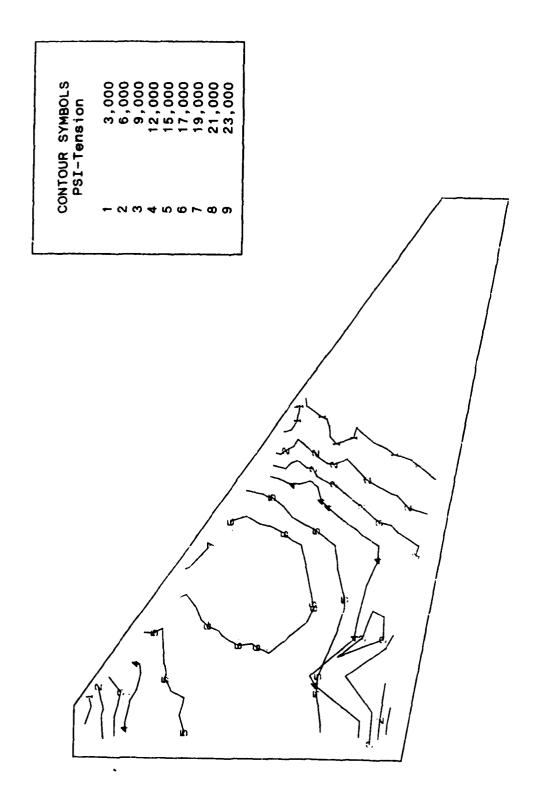
H-11

Figure H-11. Lower Wing Surface (Model DC-9R)

H-12



Stress Contours on Upper Wing Surface (Model DC-9R) Figure H-12.



Stress Contours on Lower Wing Surface (Model DC-9R) Figure H-13.

Symmetric Normal Modes for F-16 Wing Model DC-9R Givens Method Mode 1 Frequency = 10.70 Hertz

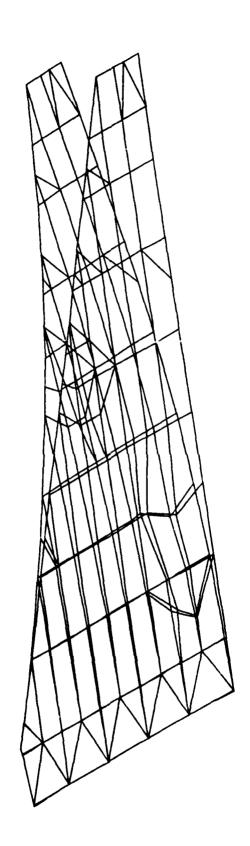


Figure H-14. 1st Wing Bending Mode (Model DC-9R)

Symmetric Normal Modes for F-16 Wing Model DC-9R Givens Method Mode 2 Frequency = 35.06 Hertz

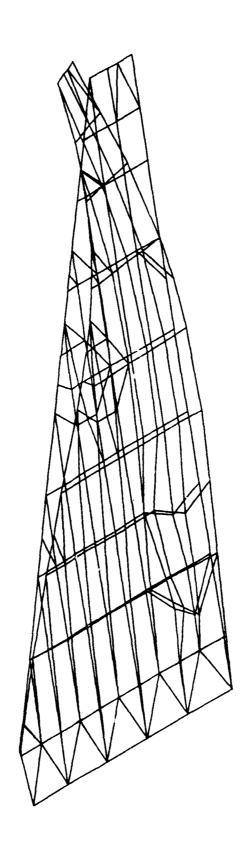


Figure H-15. 2nd Wing Bending Mode (Model DC-9R)

Symmetric Normal Modes for F-16 Wing Model DC-9R Givens Method Mode 3 Frequency = 45.67 Hertz

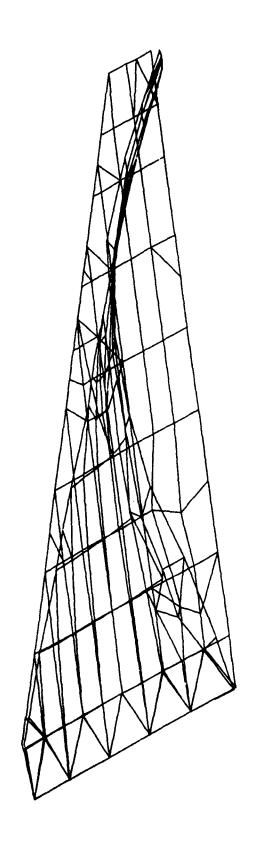


Figure H-16. 1st Torsional Mode (Model DC-9R)

Symmetric Normal Modes for F-16 Wing Model DC-9R Givens Method Mode 4 Frequency = 65.79 Hertz

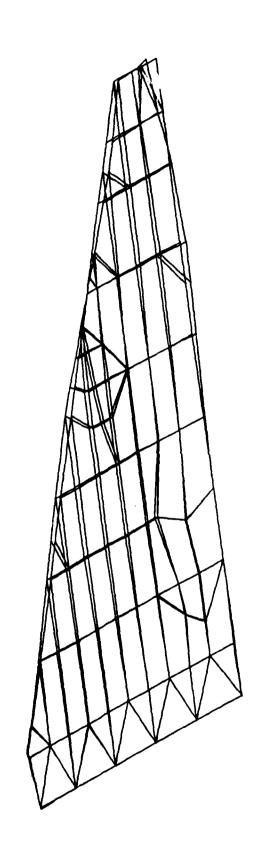
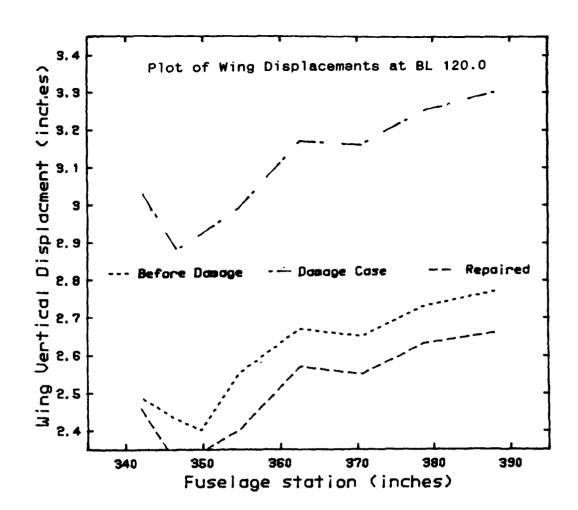


Figure H-17. 2nd Torsional Mode (Model DC-9R)

APPENDIX I

ANALYSIS OF DAMAGE CASE #12



Tabulated Displacements Fuselage St. 387.9 378.6 370.6 362.6 354.6 349.7 346.6 341.9

								
Model DC-9R	2.77	2.73	2.65	2.67	2.55	2.40	2.43	2.49
Model DC-12	3.30	3.25	3.16	3.17	2.99	2.92	2.88	3.04
Model DC-12R	2.66	2.63	2.55	2.57	2.40	2.34	2.31	2.46

Comparison of Residual Strength Av Disp % Change Torsion mode % Change 2.59 45.67 Model DC-12 -19.343.87 -3.93.09 Model DC-9R 2.59 +23.2 45.54 +3.7

Figure I-1. Summary of Damage Case #12 Results

Model DC-9

Figure I-2. Upper Wing Surface (Model DG-12)

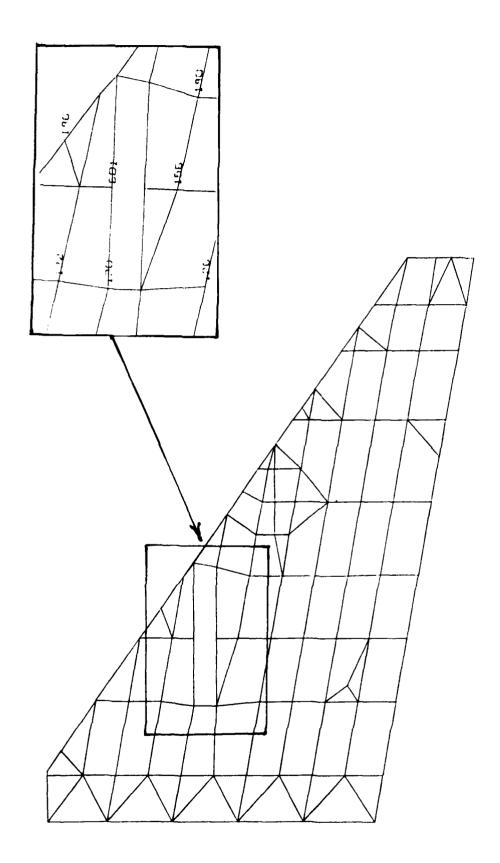
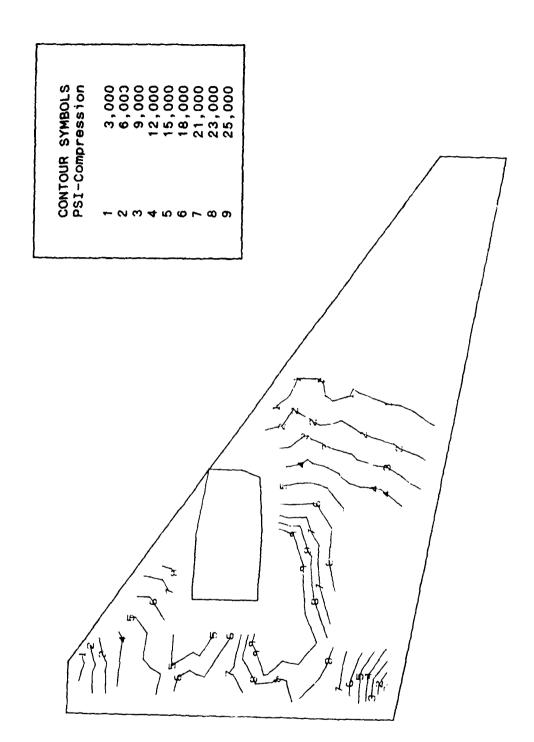
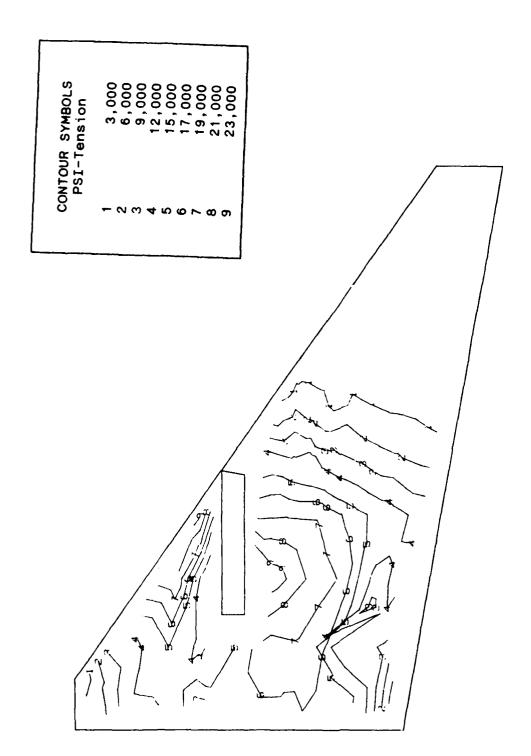


Figure I-3. Lower Wing Surface (Model DG-12)



Stress Contours on Upper Wing Surface (Model DC-12) Figure I-4.



Stress Contours on Lower Wing Surface (Model DC-12) Figure I-5.

Symmetric Normal Modes for F-16 Wing Model DC-12 Givens Method Mode 1 Frequency = 9.88 Hertz

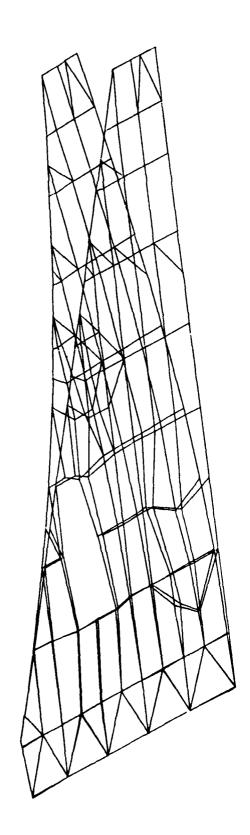


Figure I-6. 1st Wing Bending Mode (Model DC-12)

Symmetric Normal Modes for F-16 Wing Model DC-12 Givens Method Mode 2 Frequency = 34.14 Hertz

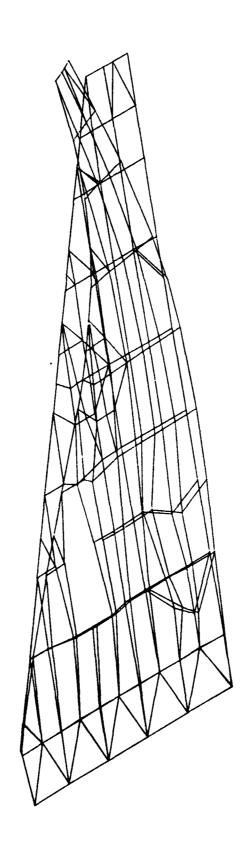


Figure I-7. 2nd Wing Bending Mode (Model DC-12)

Symmetric Normal Modes for F-16 Wing Model DC-12 Givens Method Mode 3 Frequency = 43.87 Hertz

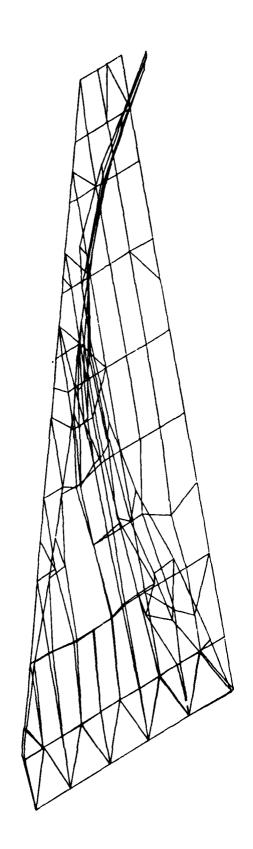


Figure I-8. 1st Torsional Mode (Model DC-12)

Symmetric Normal Modes for F-16 Wing Model DC-12 Givens Method Mode 4 Frequency = 66.29 Hertz

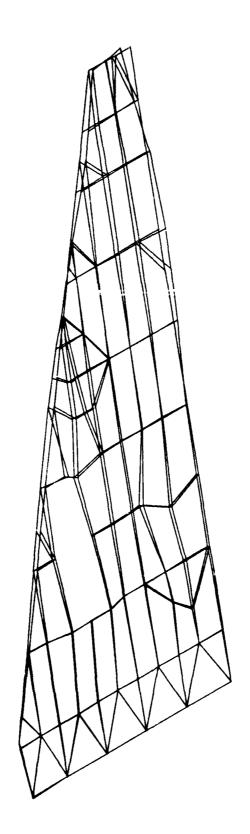


Figure I-9. 2nd Torsional Mode (Model DC-12)

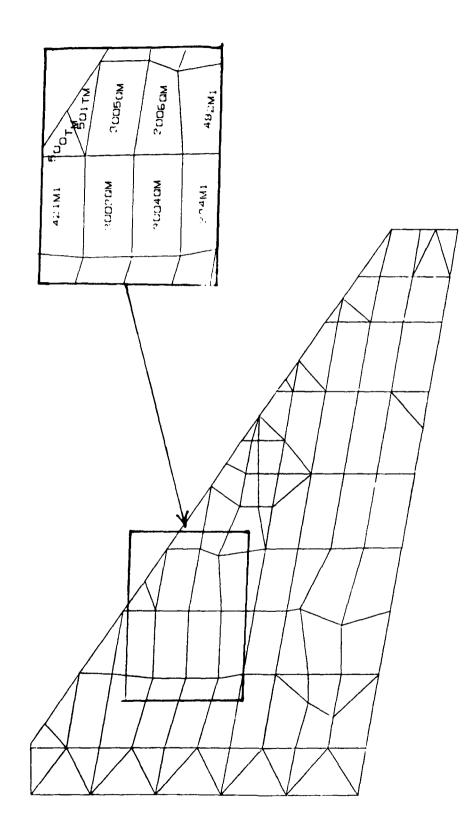
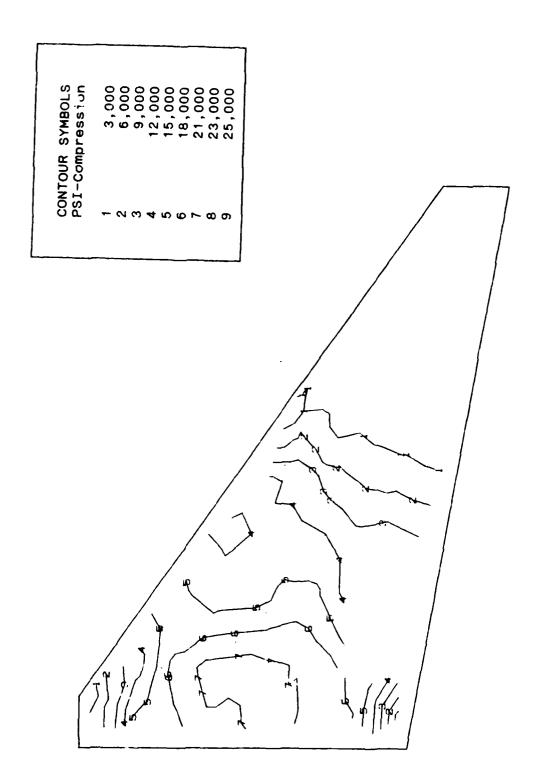
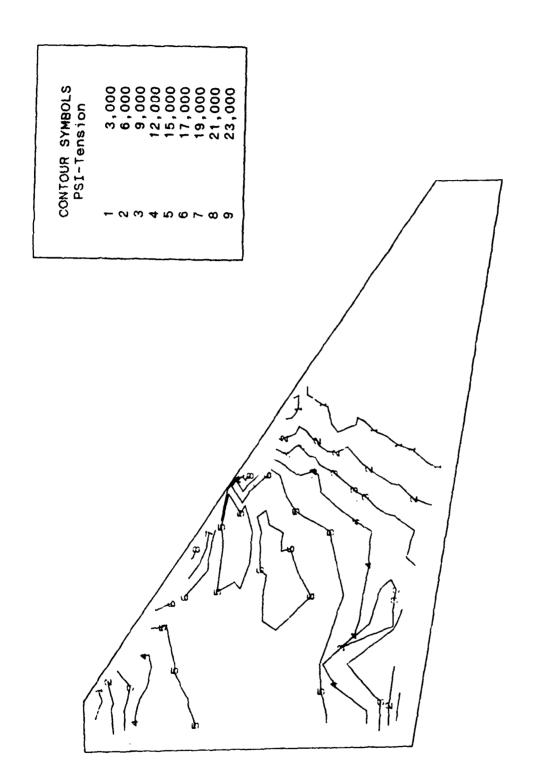


Figure I-10. Upper Wing Surface (Model DC-12R)

Figure I-11. Lower Wing Surface (Model DC-12R)



Stress Contours on Upper Wing Surface (Model DC-12R) Figure I-12.



Stress Contours on Lower Wing Surface (Model DC-12R) Figure I-13.

Symmetric Normal Modes for F-16 Wing Model DC-12R Givens Method Mode 1 Frequency = 10.86 Hertz

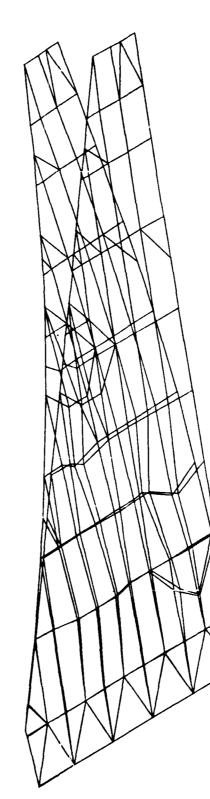


Figure I-14. 1st Wing Bending Mode (Model DC-12R)

Symmetric Normal Modes for F-16 Wing Model DC-12R Givens Method Mode 2 Frequency = 34.87 Hertz

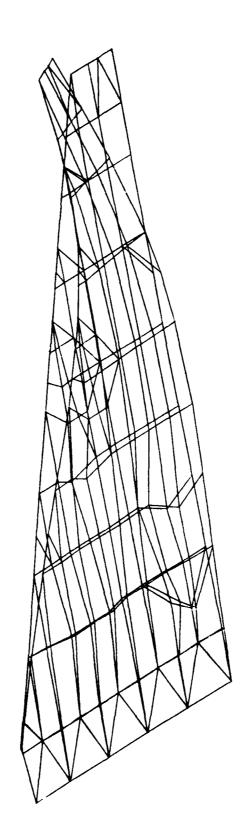


Figure I-15. 2nd Wing Bending Mode (Model DC-12R)

Symmetric Normal Modes for F-16 Wing Model DC-12R Givens Method Mode 3 Frequency = 45.54 Hertz

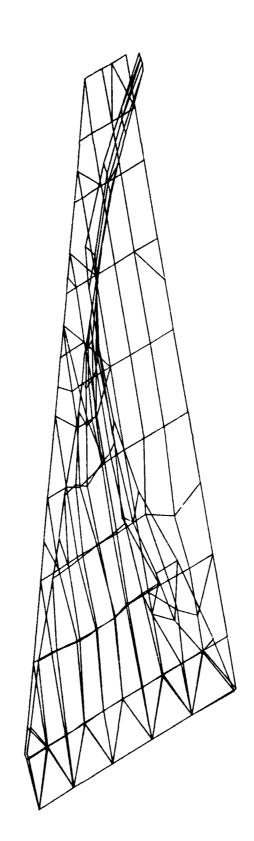


Figure I-16. 1st Torsional Mode (Model DC-12R)

Symmetric Normal Modes for F-16 Wing Model DC-12R Givens Method Mode 4 Frequency = 65.37 Hertz

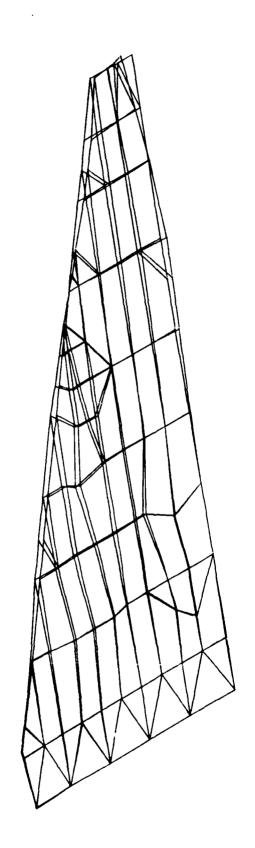
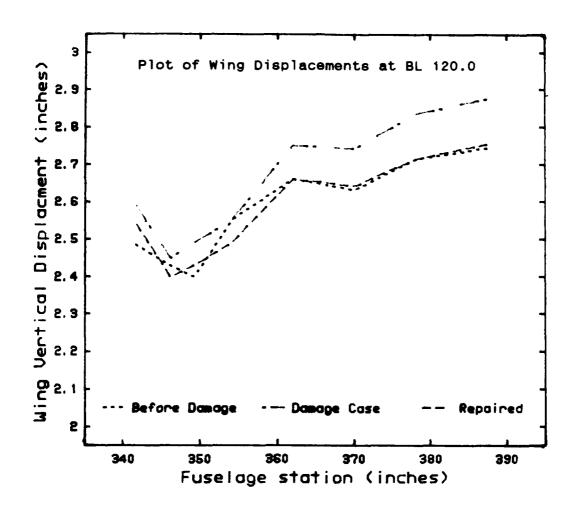


Figure I-17. 2nd Torsional Mode (Model DC-12R)

APPENDIX J

ANALYSIS OF DAMAGE CASE #15



Tabulated Displacements 387.9 378.6 370.6 362.6 354.6 349.7 346.6 341.9 Fuselage St. 2.49 Model D-4 2.74 2.71 2.63 2.66 2.55 2.40 2.43 Model DC-15 2.83 2.74 2.55 2.49 2.45 2.60 2.87 2.75 Model DC-15R 2.71 2.66 2.49 2.43 2.40 2.55 2.75 2.64

	Comparison Av Disp	of Residual % Change	Strength Torsion mode	% Change
Model D-4	2.58		48.15	
Model DC-15	2.66	-3.1	46.10	-4.3
Model DC-15	2.58	+3.1	48.12	+4.2

Figure J-1. Summary of Damage Case #15 Results

Figure J-2. Upper Wing Surface (Model DC-15)

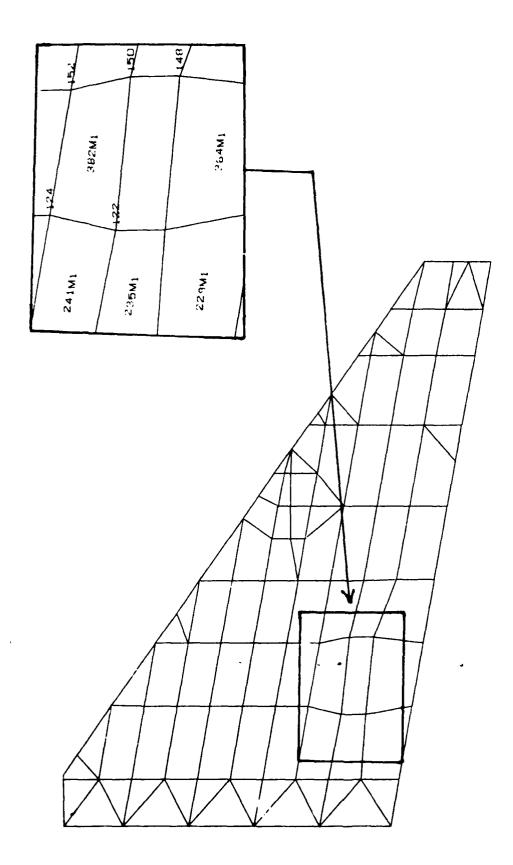
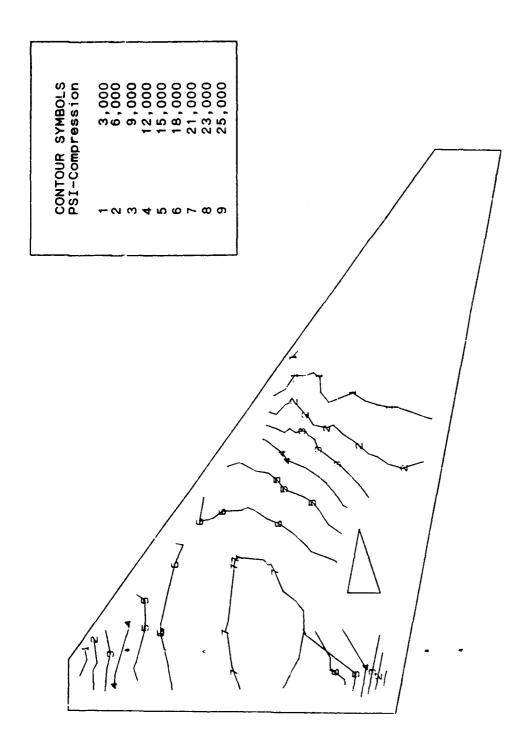
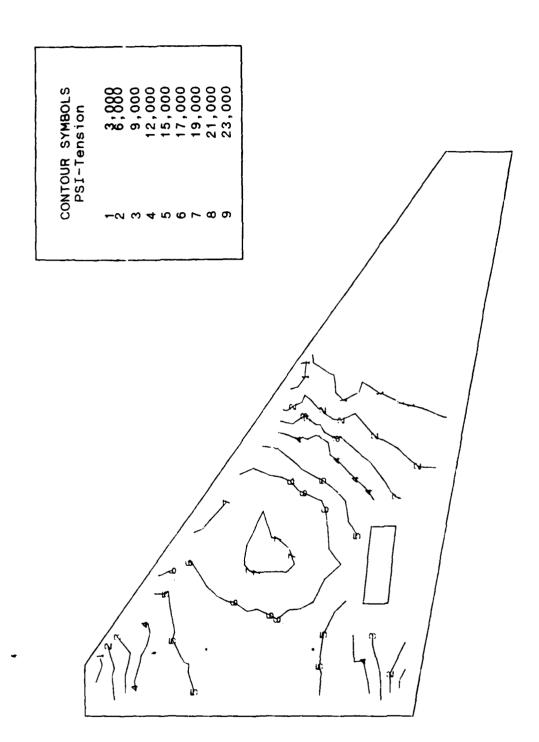


Figure J-3. Lower Wing Surface (Model DC-15)



Stress Contours on Upper Wing Surface (Model DC-15) Figure J-4.



Stress Contours on Lower Wing Surface (Model DC-15) Figure J-5.

Symmetric Normal Modes for F-16 Winy Model DC-15 Givens Method Mode 1 Frequency = 10.82 Hertz

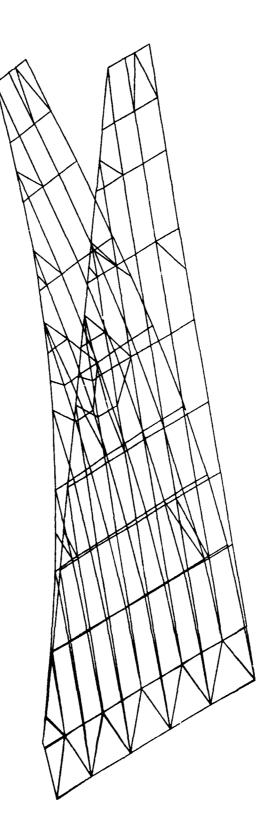


Figure J-6. 1st Wing Bending Mode (Model DC-15)

Symmetric Normal Modes for F-16 Wing Model DC-15 Givens Method Mode 2 Frequency = 36.69 Hertz

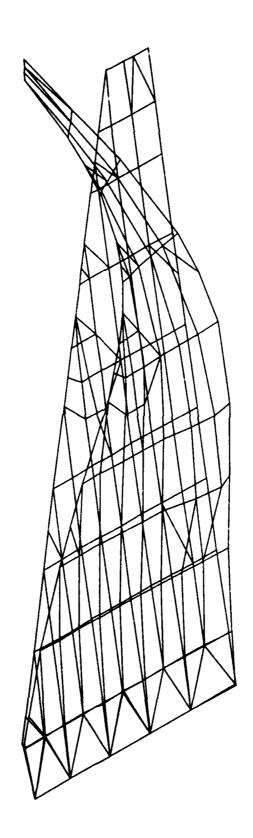


Figure J-7. 2nd Wing Bending Mode (Model DC-15)

Symmetric Normal Modes for F-16 Wing Model DC-15 Givens Method Mode 3 Frequency = 46.10 Hertz

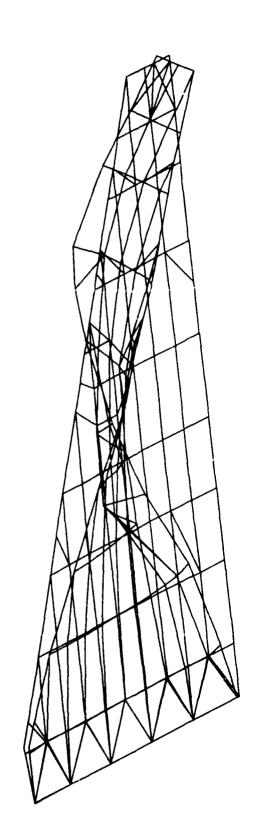


Figure J-8. 1st Torsional Mode (Model DC-15)

Symmetric Normal Modes for F-16 Wing Model DC-15 Givens Method Mode 4 Frequency = 73.39 Hertz

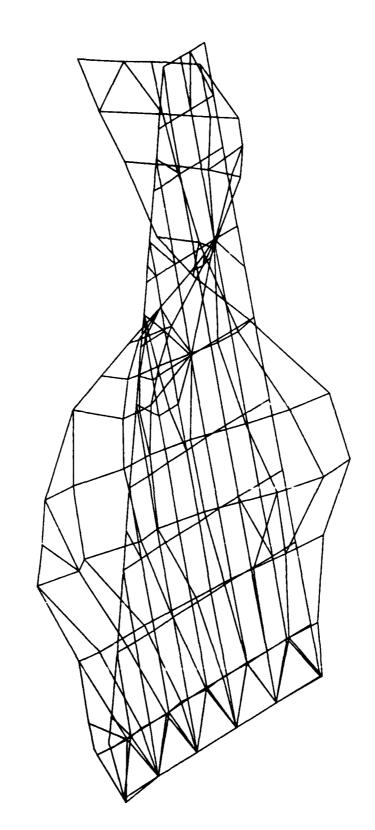
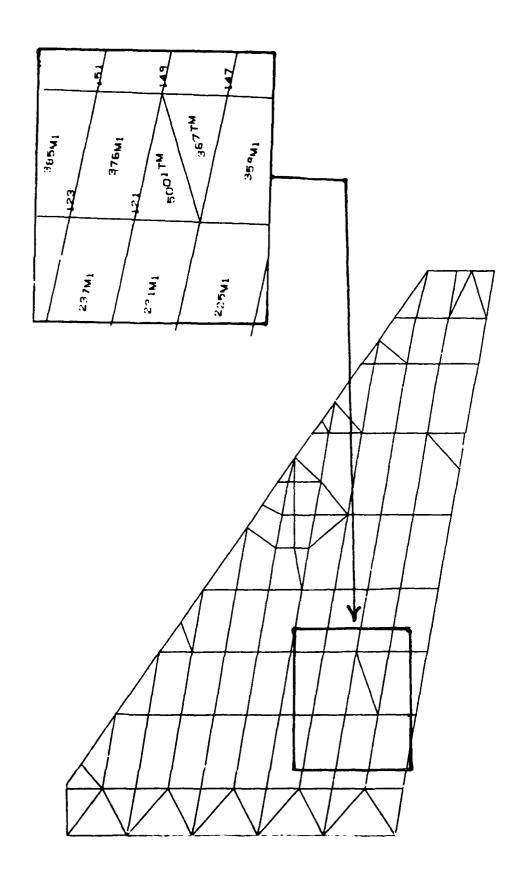


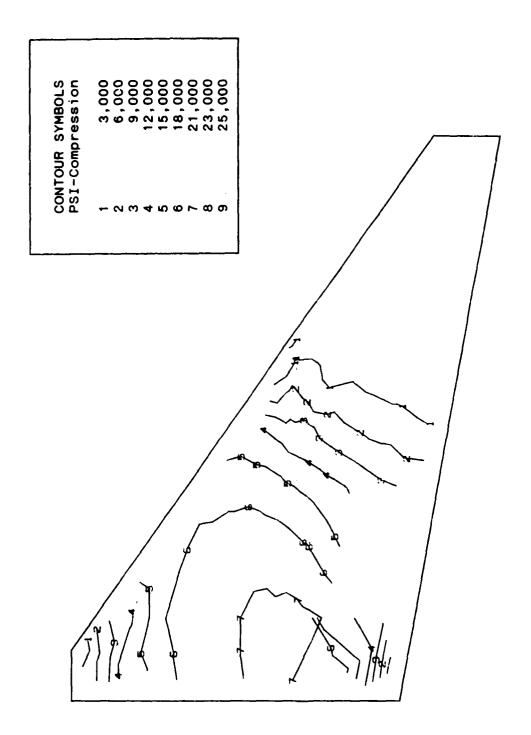
Figure J-9. 2nd Torsional Mode (Model DC-15)



J-11

Figure J-11. Lower Wing Surface (Model DC-15R)

J-12



J-13

Stress Contours on Lower Wing Surface (Model DC-15R) Figure J-13.

Symmetric Normal Modes for F-16 Wing Model DC-15R Givens Method Mode 1 Frequency = 10.93 Hertz

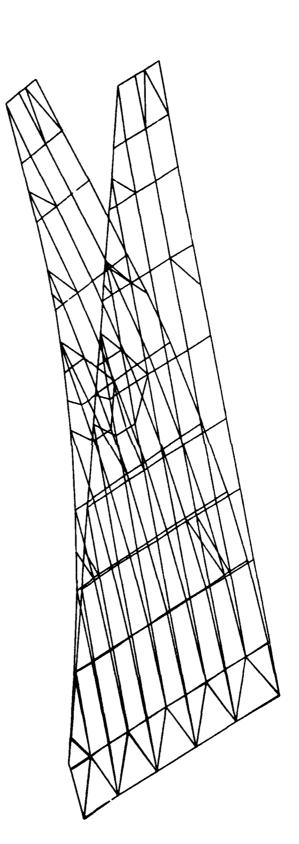


Figure J-14. 1st Wing Bending Mode (Model DC-15R)

Symmetric Normal Modes for F-16 Wing Model DC-15R Givens Method Mode 2 Frequency = 37.28 Hertz

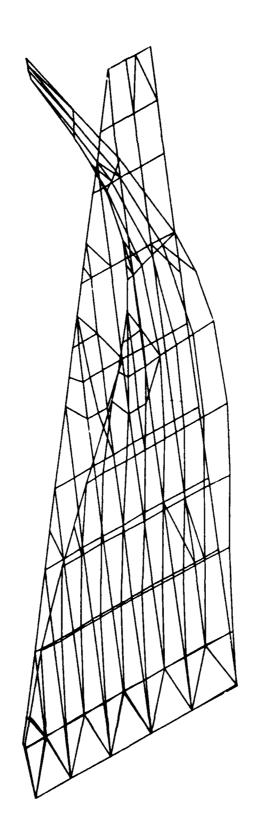


Figure J-15. 2nd Wing Bending Mode (Model DC-15R)

Symmetric Normal Modes for F-16 Wing Model DC-15R Givens Method Mode 3 Frequency = 48.12 Hertz

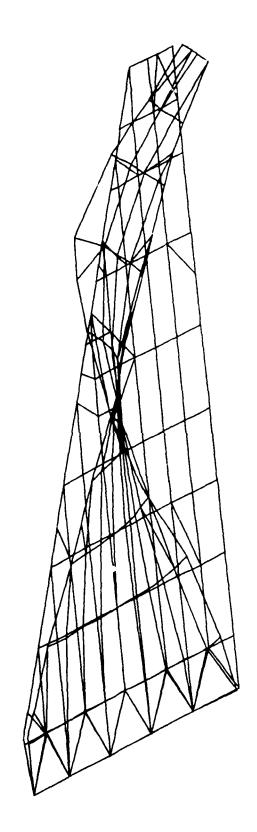


Figure J-16. 1st Torsional Mode (Model DC-15R)

Symmetric Normal Modes for F-16 Wing Model DC-15R Givens Method Mode 4 Frequency = 77.50 Hertz

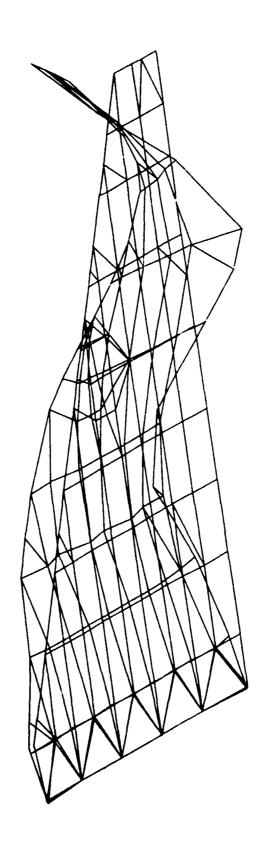
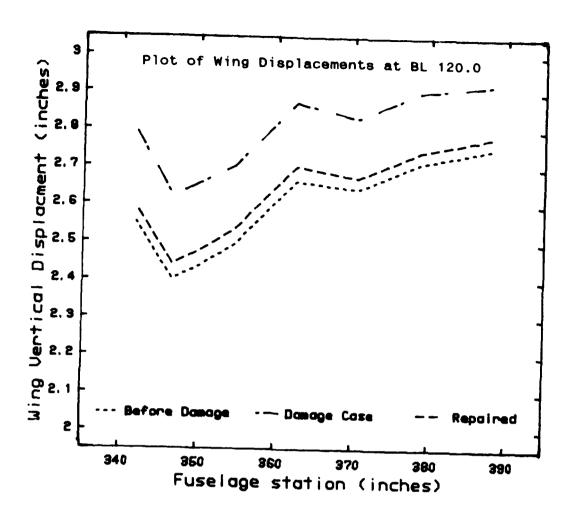


Figure J-17. 2nd Torsional Mode (Model DC-15R)

APPENDIX K

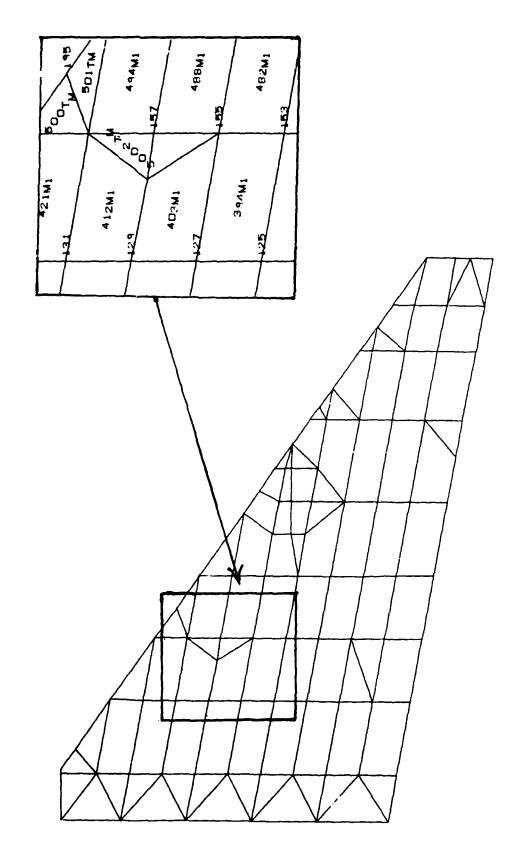
ANALYSIS OF DAMAGE CASE #16



Tabulated Displacements Fuselage St. 387.9 378.6 370.6 362.6 354.6 349.7 346.6 341.9 Model D-15R 2.75 2.71 2.64 2.66 2.49 2.43 2.40 2.55 Model DC-16 2.92 2.90 2.83 2.87 2.65 2.70 2.62 2.79 Model DC-16R 2.78 2.74 2.67 2.70 2.53 2.47 2.44 2.59 Comparison of Residual Strength Av Disp % Change Torsion mode % Change

1					
	Model D-15R	2.58		48.12	
Ì	Model DC-16	2.79	-8.1	46.13	-4.1
	Model DC-16R	2.62	+6.6	48.13	+4.1

Figure K-1. Summary of Damage Case #16 Results



K-3

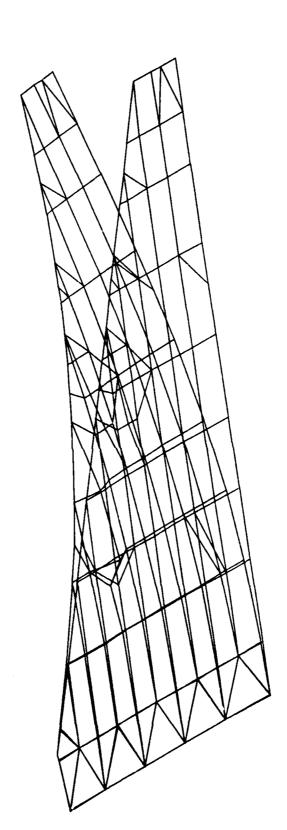
Figure K-3. Lower Wing Surface (Model DC-16)

K-4

Stress Contours on Upper Wing Surface (Model DC-16) Figure K-4.

Stress Contours on Lower Wing Surface (Model DC-16) Figure K-5.

Symmetric Normal Modes for F-16 Wing Model DC-16 Givens Method Mode 1 Frequency = 10.89 Hertz



Symmetric Normal Modes for F-16 Wing Model DC-16 Givens Method Mode 2 Frequency = 36.20 Hertz

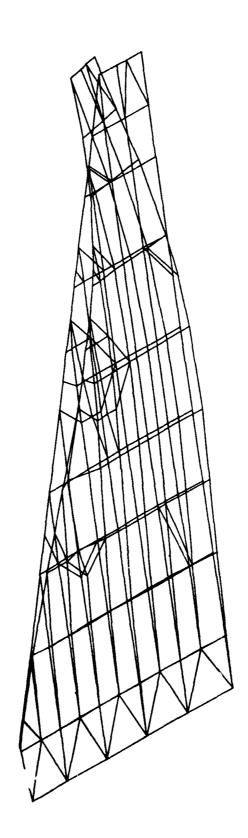


Figure K-7. 2nd Wing Bending Mode (Model DC-16)

Symmetric Normal Modes for F-16 Wing Model DC-16 Givens Method Mode 3 Frequency = 46.13 Hertz

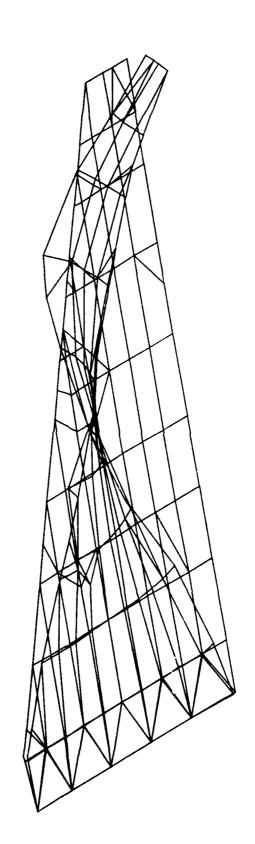


Figure K-8. 1st Torsional Mode (Model DC-16)

Symmetric Normal Modes for F-16 Wing Model DC-16 Givens Method Mode 4 Frequency = 76.37 Hertz

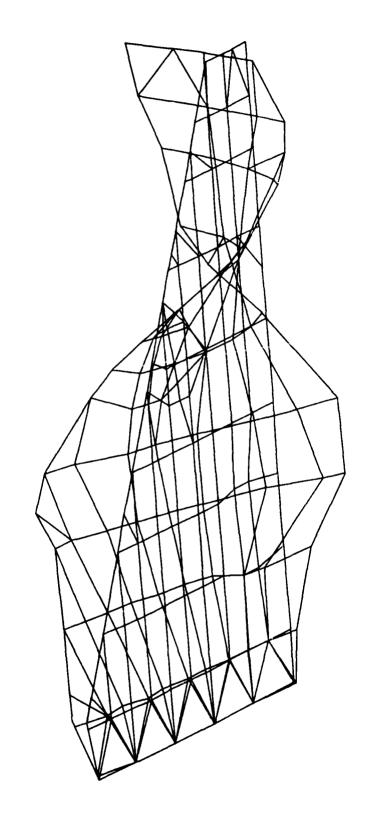


Figure K-9. 2nd Torsional Mode (Model DC-16)

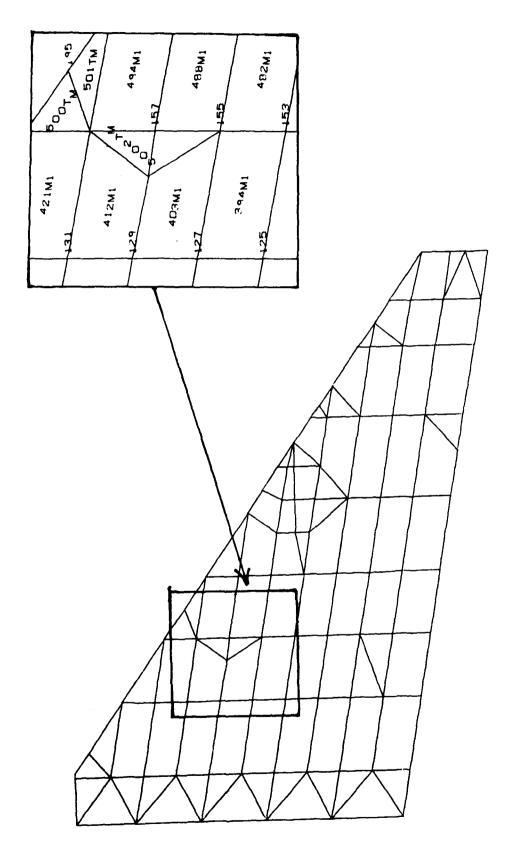


Figure K-10. Upper Wing Surface (Model DC-16R)

K-11

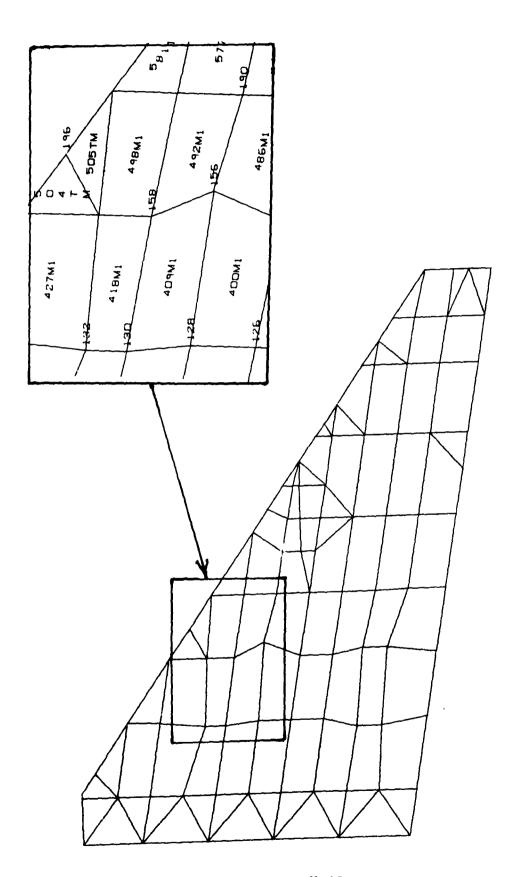


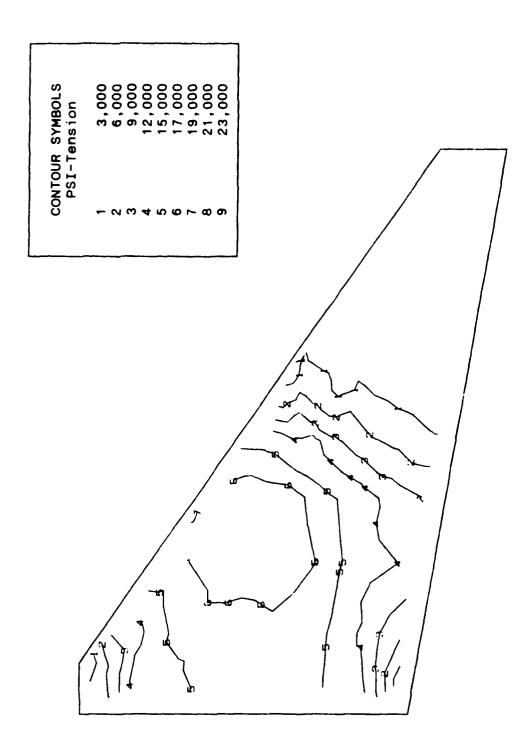
Figure K-11. Lower Wing Surface (Model DC-16R)

K-12

Stress Contours on Upper Wing Surface (Model DC-16R) Figure K-12.

K-13

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Stress Contours on Lower Wing Surface (Model DC-16R) Figure K-13.

K - 14

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Symmetric Normal Modes for F-16 Wing Model DC-16R Givens Method Mode 1

Frequency = 10.93 Hertz

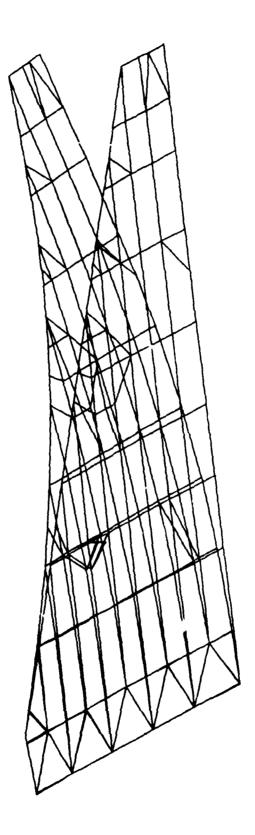


Figure K-14. 1st Wing Bending Mode (Model DC-16R)

Symmetric Normal Modes for F-16 Wing Model DC-16R Givens Method Mode 2 Frequency = 37.50 Hertz

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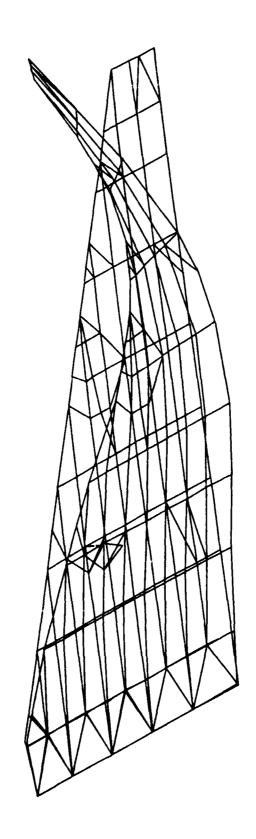


Figure K-15. 2nd Wing Bending Mode (Model DC-16R)

Symmetric Normal Modes for F-16 Wing Model DC-16R Givens Method Mode 3 Frequency = 48.13 Hertz

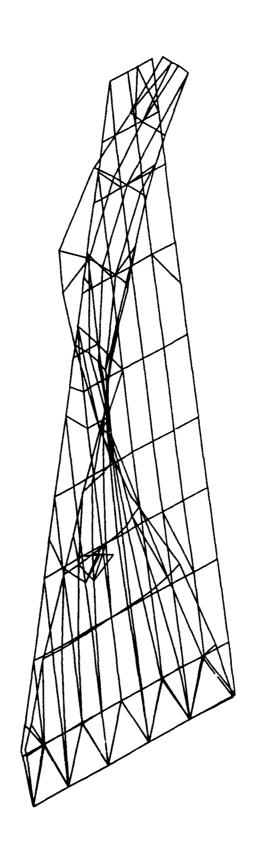


Figure K-16. 1st Torsional Mode (Model DC-16R)

Symmetric Normal Modes for F-16 Wing Model DC-16R Givens Method Mode 4 Frequency = 78.37 Hertz

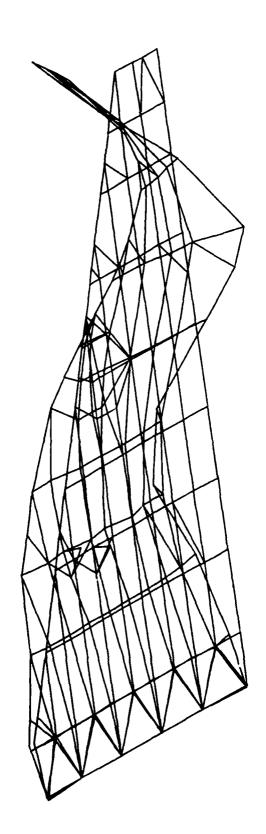
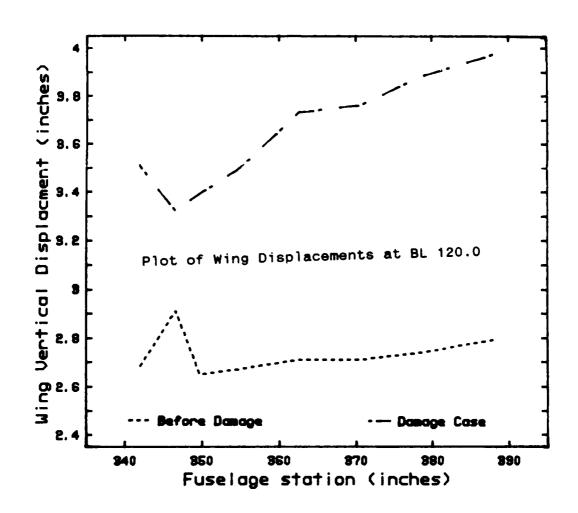


Figure K-17. 2nd Torsional Mode (Model DC-16R)

APPENDIX L

ANALYSIS OF DAMAGE CASE #17



Tabulated Displacements Fuselage St. 387.9 378.6 370.6 362.6 354.6 349.7 346.6 341.9 Model D-16R 2.74 2.78 2.67 2.70 2.53 2.47 2.44 2.59 Model DC-17 3.97 3.88 3.76 3.73 3.49 3.39 3.32 3.51 Comparison of Residual Strength Av Disp % Change % Change Torsion mode Model D-16R 2.62 48.13 Model DC-17 3.79 -44.746.13 -4.1

Figure L-1. Summary of Damage Case #17 Results

Figure L-2. Upper Wing Surface (Model DC-17)

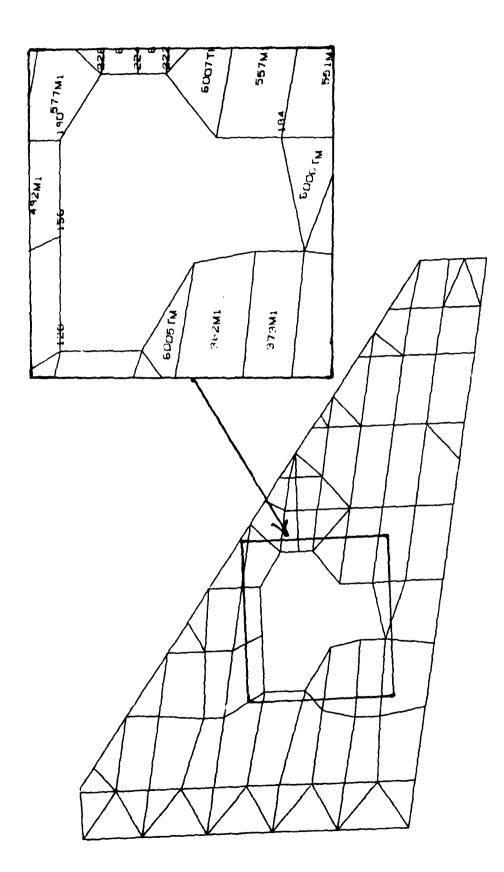
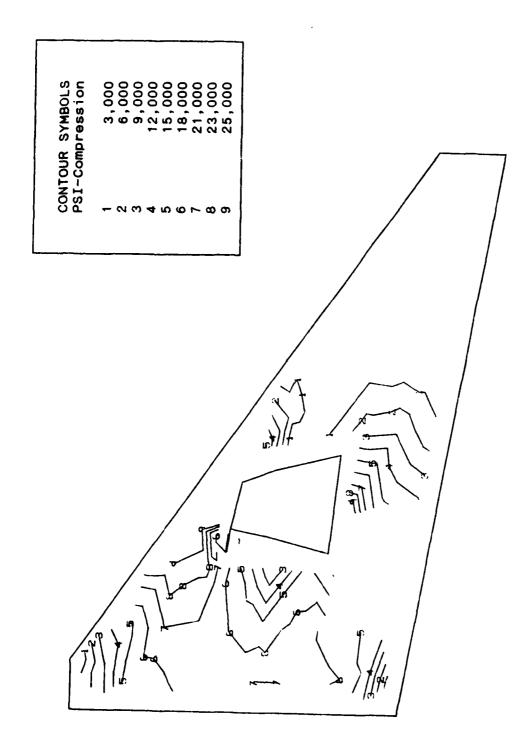
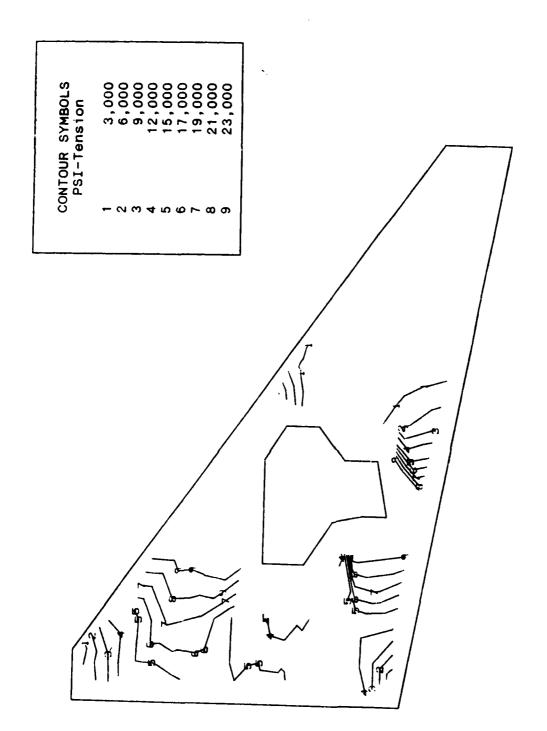


Figure L-3. Lower Wing Surface (Model DC-17)



Stress Contours on Upper Wing Surface (Model DC-17) Figure L-4.

Hotel State of the State of the



Stress Contours on Lower Wing Surface (Model DC-17) Figure L-5.

Symmetric Normal Modes for F-16 Wing Model DC-17 Givens Method Mode 1 Frequency = 8.96 Hertz

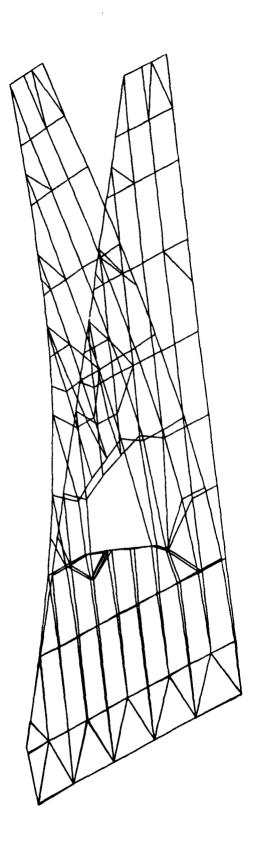


Figure L-6. 1st Wing Bending Mode (Model DC-17)

Symmetric Normal Modes for F-16 Wing Model DC-17 Givens Method Mode 2 Frequency = 36.21 Hertz

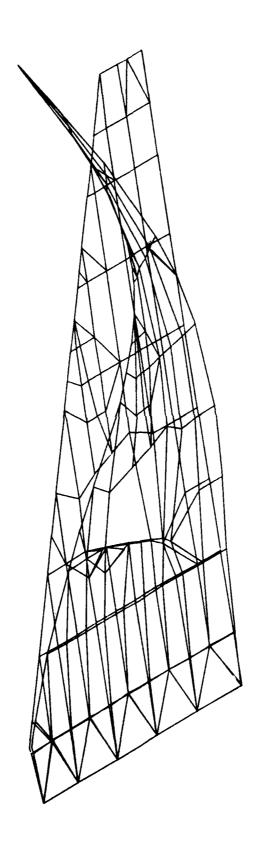


Figure L-7. 2nd Wing Bending Mode (Model DC-17)

Symmetric Normal Modes for F-16 Wing Model DC-17 Givens Method Mode 3 Frequency = 46.64 Hertz

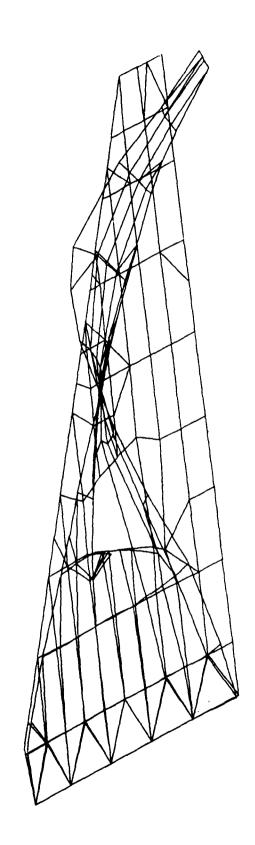


Figure L-8. 1st Torsional Mode (Mode) DC-17)

Symmetric Normal Modes for F-16 Wing Model DC-17 Givens Method Mode 4 Frequency = 75.70 Hertz

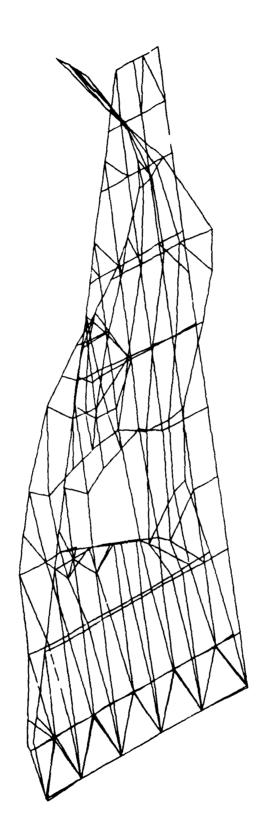


Figure L-9. 2nd Torsional Mode (Model DC-17)